



Modelling approaches for the assessment of projected impacts of drivers of change on biodiversity, ecosystems functions and aquatic ecosystems service delivery

Deliverable 7.1



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List of abbreviations

ARIES	Artificial Intelligence for Ecosystem Services
BBN	Bayesian Belief Network
CBD	Convention on Biological Diversity
EBM	Ecosystem-based management
EF	Ecosystem function
ESS	Ecosystem services
IPBES	Intergovernmental Science–Policy Platform on Biodiversity and Ecosystem Services
MAES	Mapping and Assessment of Ecosystems and their Services
PU	Planning unit
SDM	Species Distribution Model
WP	Work Package



About AQUACROSS

Knowledge, Assessment, and Management for AQUatic Biodiversity and Ecosystem Services aCROSS EU policies (AQUACROSS) aims to support EU efforts to protect aquatic biodiversity and ensure the provision of aquatic ecosystem services. Funded by Europe's Horizon 2020 research programme, AQUACROSS seeks to advance knowledge and application of ecosystem-based management for aquatic ecosystems to support the timely achievement of the EU 2020 Biodiversity Strategy targets.

Aquatic ecosystems are rich in biodiversity and home to a diverse array of species and habitats, providing numerous economic and societal benefits to Europe. Many of these valuable ecosystems are at risk of being irreversibly damaged by human activities and pressures, including pollution, contamination, invasive species, overfishing and climate change. These pressures threaten the sustainability of these ecosystems, their provision of ecosystem services and ultimately human well-being.

AQUACROSS responds to pressing societal and economic needs, tackling policy challenges from an integrated perspective and adding value to the use of available knowledge. Through advancing science and knowledge; connecting science, policy and business; and supporting the achievement of EU and international biodiversity targets, AQUACROSS aims to improve ecosystem-based management of aquatic ecosystems across Europe.

The project consortium is made up of sixteen partners from across Europe and led by Ecologic Institute in Berlin, Germany.

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1 Background

Building on previous work in AQUACROSS, management of aquatic ecosystems involves assessing the drivers and pressures in relation to affected ecosystem components, ecosystem functions (EF) and ecosystem services (ESS) of a system and making educated decisions about the response of those components to changes.

This report introduces and reviews the application of different modelling approaches to evaluate projected changes of drivers and pressures within the AQUACROSS Assessment Framework according to (participatory) scenarios across the different aquatic realms. In this report, we select models in respect of possible integration across different aquatic realms, consideration and quantification of uncertainty, and applicability across different spatial and temporal scales, as well as taking into account human adaptive behaviour. Modelling approaches previously identified in the project are adjusted for implementation in the case studies, and guidelines are presented for their practical application to ensure consistent modelling across the different aquatic realms.

This report has strong ties to previous work within AQUACROSS, and builds upon the insights especially derived from the AQUACROSS Innovative Concept and Assessment Framework (Gómez et al. 2016, Gómez et al. 2017). Aiming for a sustainable ecosystem-based management (EBM) and linking the ecological and socio-economic system, the modelling frameworks described in this report mimic the sequence of the single steps of the AQUACROSS Assessment Framework (Figure 1). Regarding EBM, these two systems interact through the supply versus demand of ESS. On the one hand, it is crucial to analyse the supply as a capacity of the ecological system to fulfil social demands of ESS by EF (i.e., providing human welfare). On the other hand, it remains compelling to analyse the demand of ESS by the socio-economic system, and how it in turn affects the structure and functioning of the ecological system (Gómez et al. 2017; Deliverable 3.2). Hence, any analyses that apply the AQUACROSS Assessment Framework need to consider this feedback mechanism, either by using observed data and processes (i.e., analyse the past), or by scenarios as potential alternative pathways. While the past is obviously constrained by the actions taken at a given time, therefore not giving much freedom to assess changes in management options, scenarios can overcome this limitation by asking the question of how the supply and demand sides could change, given a potential action strategy. Here, modelling approaches are essential to (1) assess the status quo of the interplay between biodiversity, EF and ESS, and to (2) subsequently generate scenario projections on alternative management actions or environmental changes while simultaneously assessing potential uncertainties stemming from the available data, tools and assumptions. Moreover, models can be applied on various spatial and temporal scales and allow the tuning and adjusting of single parameters while controlling others.

Further, this report builds on the previous Deliverables 4.1 (Pletterbauer et al. 2016) and 5.1 (Nogueira et al. 2016), by relying on the guidance of (i) how to assess drivers and pressures, and (ii) in choosing the tools for assessing causality between biodiversity, EF and ESS.

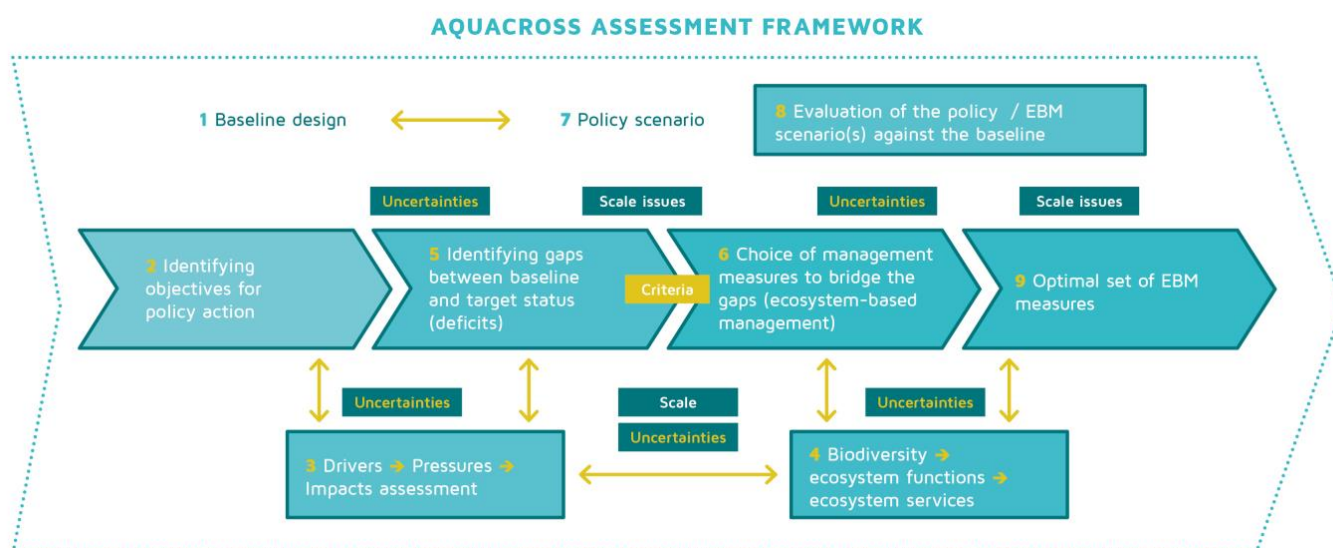


Figure 1: The AQUACROSS Assessment Framework sequence

Source: (Gómez et al. 2017; Deliverable 3.2)

Specifically, for any subsequent modelling approach making the Assessment Framework operational, it is important to assess which drivers and pressures are relevant across the aquatic realms, suitable methods to analyse them, and analyse which indicators should be considered (Pletterbauer et al. 2016; Deliverable 4.1). Likewise, this report extends on the recommendations given by Deliverable 5.1 in terms of identifying the main links between the ecological and socio-economic systems, as well as the modelling tools that could be used (Nogueira et al. 2016; Deliverable 5.1).

The central aim of this report is to provide guidance on how to jointly assess biodiversity, EF and ESS in a qualitative or quantitative way. We provide two options: using the linkage framework (Pletterbauer et al. 2016; Deliverable 4.1, and ongoing work in Deliverable 4.2) for qualitative analyses and results (chapter 3), or a quantitative spatial modelling framework (chapter 4). While the latter has the advantage of spatially (and temporally) pinpointing specific patterns between biodiversity, EF and ESS, it also has specific requirements regarding the data (chapter 4.1) and spatial units (chapter 4.2). A variety of model components can be used to model biodiversity, EF and ESS, and to spatially prioritise these (chapter 4.3). The modelling framework allows the use of scenarios (chapter 5) to assess and iterate how environmental change and management actions would impact biodiversity and ESS (chapter 6), and to account for uncertainties in case a multi-algorithm or Bayesian approach is applied (chapter 7). These are considered key for enhancing the credibility and legitimacy of policy decisions regarding management decisions, and are envisaged to be tested within selected case study areas. Finally, we also provide potential alternatives to the proposed modelling framework in case of data deficiency (chapter 8).

2 Introduction

2.1 Current state of knowledge

Within AQUACROSS, “ESS are the final outputs from ecosystems that are directly consumed, used (actively or passively) or enjoyed by people”. Likewise, EF are defined as “a precise effect of a given constraint on the ecosystem flow of matter and energy performed by a given item of biodiversity, within a closure of constraints. EF include decomposition, production, nutrient cycling, and fluxes of nutrients and energy” (Gómez et al. 2017; Deliverable 3.2, chapter 2.5).

There is a high availability of different quantitative predictive modelling techniques for the assessment of those links, including process-based (or mechanistic models), correlative (or statistical models) or different types of quantitative (expert-based) models. The various techniques can be summarised in different categories dependent on mathematical or statistical background, data basis, static or dynamic approaches or model fitting methods (see Pletterbauer et al. 2016; Deliverable 4.1 on drivers of change and pressures on aquatic ecosystems).

Species distribution modelling (SDM, chapter 4.3.1, Figure 5) and other quantitative approaches to assess links within socio-ecological systems contain a huge variety of statistical methods that can be applied (Pletterbauer et al. 2016; Deliverable 4.1). Those include regression-based methods, which have the advantage of simplicity and produce model equations with parameters that can be directly related to scientific hypotheses. Furthermore, they can be used directly for predictions. Therefore, regression-based methods have been the main choice in modelling studies (Elith and Graham 2009, Ennis et al. 1998). In contrast, machine learning techniques (e.g., artificial neural networks, classification trees, random forests, Bayesian belief networks), a family of statistical techniques with origins in the field of artificial intelligence, are emerging tools for ecological predictive modelling approaches. They are recognised as being able to handle complex problems with multiple interacting elements (Olden et al. 2008). Additionally, there is interest in “ensemble learning” techniques (e.g., random forests, conditional inference forest, generalised boosting method), i.e. methods that generate many classifiers and aggregate their results (Guisan et al. 2006).

Although there is a strong scientific basis, predicting the outcome of specific management decisions is always associated with an unknown level of uncertainty, which stems from e.g. small data sets, unknown noise in the data and unknown level of interaction between variables. One other major identified source of relative uncertainty stems from modelling algorithms themselves (Diniz-Filho et al. 2009, Gómez et al. 2017; Deliverable 3.2).

Causality is another important factor for the assessment of the linkages within the socio-ecological system within each modelling framework (Gómez et al., 2017). The first type of evidence for causation is an association between measurements of causes and effects in space and time, including:

- ▶ strength of association (Yeung and Griffiths 2015)
- ▶ consistency (evidence that the cause co-occurs with the unaffected entity in space and time (Cormier and Suter II 2013, Norton et al. 2014)),
- ▶ temporality (evidence that the cause precedes the effect (Cormier and Suter II 2013)) or
- ▶ preceding causation (evidence that the causal relationship is a result of a larger cause-and-effect web, (Cormier and Suter II 2013, Suter et al. 2002)).

Whenever possible, these associations should be quantified within a statistical model (Suter et al. 2002). In a second step, post hoc interpretation of statistical models is causal (Dormann et al. 2012, Suter et al. 2002) based on considerations of other situations or biological knowledge. This includes plausibility (“Is a cause-and-effect relationship expected given the known facts or evidence from other studies?”), or specificity (“Is there only one known cause for one observed effect or multiple?”) (Suter et al. 2002).

Alternative qualitative methods (see Pletterbauer et al. (2016; Deliverable 4.1) for more details) can vary substantially in their performance, causal interpretability or accuracy, also dependent on the structure of available data and information, leading to implications for the implementation of different methods in the case studies.

Box 1: Lessons learnt on drivers of change and pressures on aquatic ecosystems.

- ▶ A trade-off of model complexity and accuracy versus the interpretability and causality of a model could be identified. Many machine learning and ensemble techniques produce highly reliable models with excellent performance also under high dimensionality, but this advantage comes along with a low causal interpretability, since the techniques have no simple way of graphical representation and are in most cases highly complex compared to regression and more simpler machine learning techniques. If the results should be used as a communication tool for management, simpler methods (including regression-based models) with a good graphical representation and straightforward interpretability are preferred, whereas for complex situations, including interactions and hierarchical structure of drivers and pressures, complex methods may be more advantageous. A promising tool are BBNs (Bayesian Belief Network) which are specific for their useful visual depiction and high potential to produce models of high accuracy and to include complex interactions and hierarchical structure. Quantitative BBN are an emerging tool but have so far not intensively been tested against other methods.
- ▶ A trade-off between in-sample performance versus transferability and related uncertainty was identified. This is a known trade-off between in-sample accuracy and transferability to other systems in dependency of model complexity and related to over-fitting. If model results should be general and transferable to other systems, simpler models will be more advantageous (including regression-based models).
- ▶ The quality of data-driven models is highly dependent on the quality as well as quantity of the input available data; likewise the reliability of expert-driven models is directly dependent on the available expert knowledge in the field. The selection of methods should be done dependent on the best available data and knowledge of a respective system. Combined approaches often produce the most reliable, robust and interpretable models (e.g., Bayesian approaches with the possibility to set priors).

- ▶ Model evaluation is essential for the development of reliable explanatory or predictive models, independent of whether those are based on data or experts.
- ▶ Parallel or combined application of different modelling techniques (including qualitative and quantitative methods) to the same analytical problem increases robustness and impact of results.
- ▶ Furthermore, it is then important to identify and implement adequate indicators to gain meaningful insights in relation to drivers, pressures, ecosystem components, EF and ESS.

Source: see Pletterbauer et al. (2016; Deliverable 4.1)

2.2 Towards qualitative and quantitative models of biodiversity, ecosystem functions and services

Biodiversity, EF and ESS can be analysed using a qualitative or quantitative modelling framework, and both approaches are explained in the next two chapters 3 and 4. The qualitative linkage framework is useful to assess the overall relationships and to help identify essential links among biodiversity, EF and ESS. In turn, the spatially-explicit modelling framework aims to analyse and to prioritise biodiversity, EF and ESS across the entire case study area using exact information on the, e.g. number or uniqueness of species and the magnitude of a specific EF or ESS. Both frameworks allow the use of scenarios and the quantification of uncertainty in the data, linkages and given the scenarios. The stakeholder involvement is foreseen along the entire temporal axis of the workflows. The spatially-explicit framework then yields a spatial representation of important biodiversity and management zones, and how and which amount of costs these may represent in a feasible solution, given the uncertainties (Figure 2).

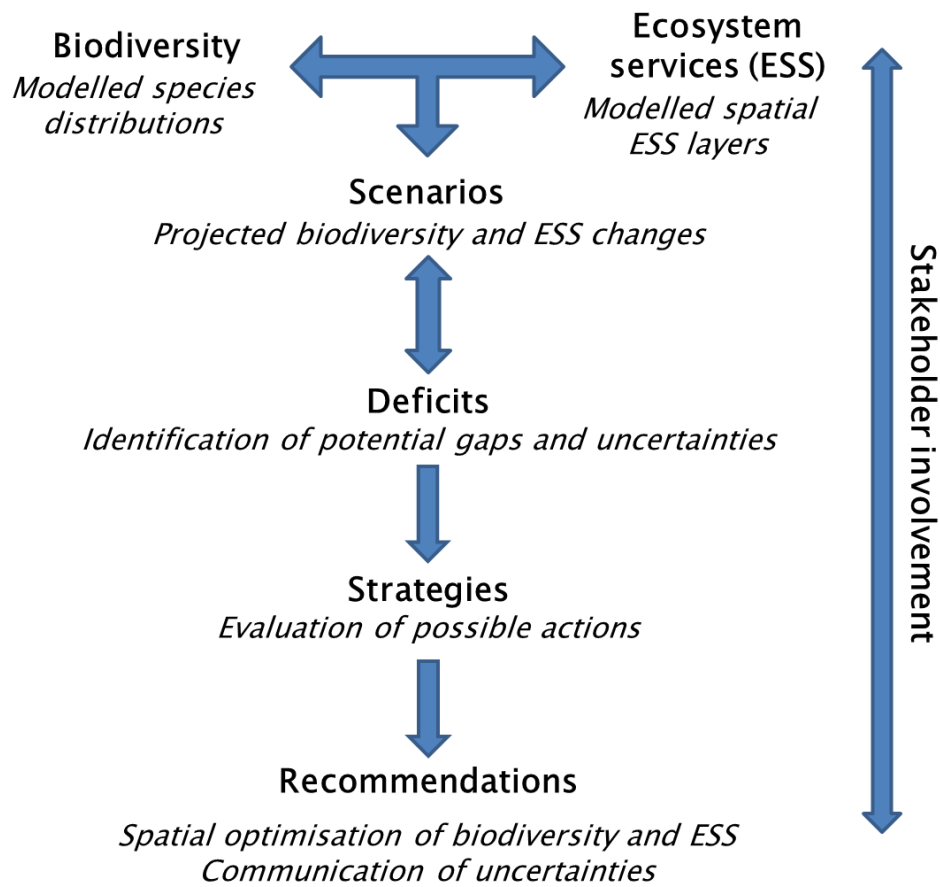


Figure 2: Generic workflow of the qualitative and quantitative (spatial) modelling.

Note: text in italics describe the results of the proposed spatial modelling workflow after each step. See also Figure 3 for a detailed description of the modelling workflow.

Source: Own elaboration

3 Qualitative Models: The Linkage Framework

3.1 Linkage matrices: a first step for coupling biodiversity and ecosystem services

The key modelled components in the social–ecological system can initially be organised in a structured way, and set in a broader context, using a linkage framework. The linkage framework is described in Pletterbauer et al. (2016; Deliverable 4.1) and Nogueira et al. (2016; Deliverable 5.1) as a way of linking the demand side of the system – the social processes, drivers, primary human activities and the pressures they cause on the ecosystem – with the supply side of the system – the ecosystem processes and functions, and the ESS they supply, leading to benefits for society (Robinson et al. 2014). The framework consists of a series of connected matrices with typologies of activities, pressures, ecosystem components, and ESS that will support policy objectives. The linkage framework acts as a central tool to organise, visualise and explore connections between different parts of the system, where linkages themselves can be analysed, as well as act as a starting point for subsequent modelling and analyses. These linkages and indicators will be provided by the ongoing work within AQUACROSS Work Package (WP) 4 (relations from the demand side) and WP5 (modelled causal links on the supply side).

In addition to the assessment of 'impact–pathways' from multiple activities on ecosystems components (WP4), it is crucial to understand how biodiversity loss may compromise EF and ESS provided. There is firm evidence demonstrating the importance of biodiversity to ecosystem functioning (e.g., Hooper et al. (2005), Loreau et al. (2001); Daam et al., in prep),¹ but evidence has also shown that biodiversity has a pivotal role for ESS as well (e.g., Balvanera et al. (2006), Worm et al. (2006) Teixeira et al., in prep).² However, such biodiversity–ESS relationships are not straightforward and several aspects need to be taken into account when testing hypotheses within modelling frameworks. The AQUACROSS linkage framework will allow exploring the complex relationships between the major ecosystem components and their capacity to perform or sustain several EF and contribute to the supply of multiple ESS or abiotic outputs. Such networks of relationships are crucial to reveal the potential joint production of multiple interconnected ESS; the synergies and trade–offs between ESS; the spatial dimension of ESS supply and demand; and the temporal dimension of ESS supply and demand variation

¹ Daam, M.A., Lillebø, A.I., and Nogueira, A.J.A. *Challenges in establishing causal links between aquatic biodiversity and ecosystem functioning* (in prep.).

² Teixeira, H., Lillebø, A.I., and Nogueira, A.J.A. *Pivotal role of Biodiversity on Ecosystem Services* (in prep.) from AQUACROSS Deliverable 5.1

over time (Koch et al. (2009); Teixeira et al., in prep). Acknowledging these complex relationships, as revealed by the linkage matrices, will ensure, for example, that modelling approaches in the case studies consider all important ecosystem components when modelling only part of the system; that they can back-link to ecosystem components compromised by the demand of several ESS; and that they account for any ESS potentially threatened by demand of other ESS (Teixeira et al., in prep). These linkage matrices can support spatial inferences, but the temporal dimension of the relationships is not captured, which is better addressed by the proposed modelling framework.

Specific linkage matrices for each case study have been developed under Milestone 11 of the project, which link primary activities, pressures, ecosystem components and ESS. These matrices are broad and comprehensive, covering all possible interactions between these elements of the system. To answer specific questions in the case studies, subsets of the linkages can be taken and considered under different contexts, such as:

- ▶ From an **ecological** perspective: what are the parts of the ecosystem most under threat and what are all the ways these components can be affected? What are all the consequences of impacts on these components, such as a change in the supply of ESS?
- ▶ From an **economic** perspective: what are the most valuable activities occurring in the case study area in terms of the monetary valuation of the demand side of ESS (Brouwer et al. 2013), and what impacts throughout the system do they have? What are the social processes and drivers of these activities?
- ▶ From a **policy** perspective: what are the various relevant policies acting on different parts of the system and in what ways might they interact or have consequences throughout the system?
- ▶ From a **stakeholder** perspective: through interacting with stakeholders, identify the parts of the system that are most relevant to them and consider these in the context of the wider network (Menzel and Teng 2010).

In this way, the linkage framework can help to identify and visualise the different system components and their manifold relationships and interlinkages, as well as to provide decision support and to explore management options (Robinson et al. 2014).

3.2 Linkage framework: a series of connected matrices

ESS are supplied through the structures, processes and functions of biotic groups, and abiotic outputs are supplied by the structures, processes and functions of physical habitats. In order to understand the socio-ecological system in a holistic way, and to link different parts of the system, it is important to consider how direct measures of service use or supply relate to the status of biodiversity and habitats, and how a change in status may lead to changes in ESS and abiotic outputs. The approach used here draws on typologies of ecosystem components and

ESS to show the links and the typologies used to relate to those reported on in EU policy (e.g., the Marine Strategy Framework Directive, Water Framework Directive, and the EU 2020 Biodiversity Strategy).

The supply of ESS and abiotic outputs can be linked to particular habitats, biotic groups, and physical attributes, such as areas of good wind supply (required for abiotic outputs). The link to habitats and physical attributes allows a spatial dimension to be considered in the assessment of the supply of ESS and abiotic outputs. Habitats (and the associated natural capital) can supply multiple ESS and abiotic outputs. Starting from a spatial unit, such as a particular habitat, the supply of these multiple services and abiotic outputs can be identified through use of the linkage framework (Pletterbauer et al. 2016; Deliverable 4.1, chapter 3.1), to identify all potential services and abiotic outputs.

Services and abiotic outputs can be used actively or passively by people³ and both supply and use can be associated to spatially defined areas, such as linking through habitats. There are different considerations of the spatial dimension of ESS. Services can be supplied and used in the same space or they can be supplied in one place but used in another, also called telecoupling (Liu et al. 2016). There are differing spatial scales over which ESS are produced versus where they are used. For example, nursery grounds of commercially exploited species may be in areas distinct to those where they are captured for consumption as adults. Thus, it will be important to consider the locations of both production and consumption of services (Balvanera et al. 2017).

The AQUACROSS definition of ESS encompasses more broadly the goods and services people get from the ecosystem, including the abiotic outputs that are not affected by changes in the biotic aspects of ecosystem state, but are affected by changes in the abiotic system, such as physical changes to habitat structure (Nogueira et al. 2016; Deliverable 5.1). The typology of ESS used in AQUACROSS (Table 1) comes from the CICES typology (Haines-Young and Potschin 2012) which has also been adopted by MAES for European ecosystem service assessments (Maes et al. 2016; Maes et al. 2013).

³ AQUACROSS definition of ESS from Deliverable 3.2 by Gómez et al. (2017): "... the final outputs from ecosystems that are directly consumed, used (actively or passively) or enjoyed by people", including those resulting from mediated biological processes and/or from abiotic components of ecosystems.

Table 1: CICES typology of ESS and abiotic outputs, taken from Nogueira et al. (2016; Deliverable 5.1)

Ecosystem services		Abiotic outputs from ecosystems	
Regulating and maintenance		Regulating and maintenance by abiotic structures	
Division	Group (includes the respective classes)	Group	Division
Nutritional	Biomass Wild plants and fauna; plants and animals from in situ aquaculture	Mineral Marine salt	Nutritional abiotic substances
	Water Surface or groundwater for drinking purposes	Non-mineral Sunlight	
Materials	Biomass Fibres and other materials from all biota for direct use or processing; genetic materials (DNA) from all biota	Metallic Poly-metallic nodules; Cobalt-Rich crusts, Polymetallic massive sulphides	Abiotic materials
	Water Surface or groundwater for non-drinking purposes	Non-metallic Sand/gravel	
Energy	Biomass Plants and fauna	Renewable abiotic energy sources Wind and wave energy	Energy
		Non-renewable abiotic energy sources Oil and gas	
Mediation of waste, toxics and other nuisances	Mediation by biota	By natural chemical and physical processes	Mediation of waste, toxics and other nuisances
	Mediation by ecosystems Combination of biotic and abiotic factors		
Mediation of flows	Mass flows	By solid (mass), liquid and gaseous (air) flows	Mediation of flows by natural abiotic structures
	Liquid flows		
	Gaseous/air flows		

Ecosystem services		Abiotic outputs from ecosystems	
Regulating and maintenance		Regulating and maintenance by abiotic structures	
Division	Group (includes the respective classes)	Group	Division
Maintenance of physical, chemical, biological conditions	Lifecycle maintenance, habitat and gene pool protection	By natural chemical and physical processes	Maintenance of physical, chemical, abiotic conditions
	Pest control		
	Soil formation and composition		
	Water conditions		
	Atmospheric composition and climate regulation		
Physical and intellectual interactions with biota, ecosystems, and seascapes [environmental settings]	Physical and experiential interactions	Physical and experiential interactions	Physical and intellectual interactions with land-/seascapes [physical settings]
	Experiential use of biota and seascapes; physical use of seascapes in different environmental settings	Experiential use of seascapes; physical use of seascapes in different physical settings	
	By physical and experiential interactions or intellectual and representational interactions	By physical and experiential interactions or intellectual and representational interactions	
	Intellectual and representational interactions scientific; education, heritage; aesthetic; entertainment	Intellectual and representational interactions scientific; education, heritage; aesthetic; entertainment	
Spiritual, symbolic and other interactions with biota, ecosystems, and seascapes [environmental settings]	Spiritual and/or emblematic symbolic; sacred and/or religious	Spiritual and/or emblematic symbolic; sacred and/or religious	Spiritual, symbolic and other interactions with land-/seascapes [physical settings]
	Other cultural outputs existence; bequest	Other cultural outputs existence; bequest	

Ecosystem components supply ESS through their structural properties and through the processes and functions they carry out, by means of several underlying biodiversity and EF mechanisms (Nogueira et al. 2016; Deliverable 5.1). As described above, ecosystem components can be linked to the ESS they provide in a linkage matrix format. The links represent the different ways that ecosystem components supply services, such as through filtration leading to waste treatment, accumulation of biomass leading to biomass for nutrition, existence leading to aesthetic services. People can use services actively or passively and both service supply and use can be associated to spatially defined areas. There are different considerations of the spatial dimension of ESS. A typology of ecosystem components, which includes habitats, can allow the supply and/or use of services to be linked to spatially defined habitats. Some services are delivered by mobile biotic groups (e.g., marine mammals) which cannot be so easily associated with spatially defined areas. With these services, the use of the service may be associated to a particular habitat (e.g., whale watching in coastal waters), but the supply of the service may be associated with many habitats (e.g., the full range of habitats supporting whale populations). In these cases, it may be more appropriate to consider the supply of the service from the biotic group itself rather than a spatially defined area, i.e. the supply of ESS does not always have a spatial dimension, even if the use does. A typology of ecosystem components which includes both habitats which can be spatially defined and mobile biotic groups allows the links between biodiversity and ESS to be identified and subsequently modelled. The typology of ecosystem components used here is made up of EUNIS habitat types (Table 2 below). Here we consider to include these, where the sedentary or passive biotic groups are considered a part of the habitat (e.g., macroalgae in intertidal rock habitats), and mobile biotic groups (e.g., birds, fish or mammals) are explicitly expressed due to their reliance on multiple habitats (Culhane et al. 2014). The typology of ESS and abiotic outputs⁴ draws on CICES, the EU reference typology (Table 1). On the other hand, the supply of a service may be spatially defined while the use is difficult to pinpoint to specific scales (Hein et al. 2006). For example, the rate of drawdown of carbon dioxide from the atmosphere may depend on the spatial extent of angiosperms, macroalgae or water column with phytoplankton, but the use of this service – the regulation of the global climate – has a global spatial dimension.

⁴ The evolution of the concept of Ecosystem Services (ESS) is reviewed in Deliverable 5.1 by (Nogueira et al. 2016)

Table 2: Typology of ecosystem components (habitats and biotic groups) for European aquatic ecosystems

Habitat – Realm		Habitat EUNIS Level 2
Habitat	Coastal/Inlets – Transitional	A1 Littoral rock and other hard substrata
		A2 Littoral sediment
		A3 Infralittoral rock and other hard substrata
	Coastal/Shelf/Inlets – Transitional	A4 Circalittoral rock and other hard substrata
		A5 Sublittoral sediment
	Coastal/Oceanic/Inlets – Transitional	A6 Deep sea bed
	Coastal/Oceanic/Shelf/Inlets – Transitional	A7 Pelagic water column
	Inlets – Transitional	J5 Highly artificial man made waters and associated structures
	Coastal/Terrestrial	B1 Coastal dunes and sandy shores
	Lakes	C1 Surface standing waters
	Rivers	C2 Surface running waters
	Wetlands	C3 Littoral zone of inland surface waterbodies
		D5 Sedge and reedbeds normally without free standing water
	Riparian	E1 Dry grasslands
		E2 Mesic grasslands
		E3 Seasonally wet and wet grasslands
		E5 Woodland fringes and clearings and tall forb stands
		E7 Sparsely wooded grasslands
		G1 Broadleaved deciduous woodland
		G3 Coniferous woodland
G4 Mixed deciduous and coniferous woodland		
Other	G5 Lines of trees small anthropogenic woodlands recently felled woodland early stage woodland and coppice	
	I1 Arable land and market gardens	
	J1 Buildings of cities towns and villages	
	J2 Low density buildings	
	X10 Mosaic landscapes with a woodland element bocages	
Mobile Biotic Group	Insects (<i>adults</i>)	
	Fish & Cephalopods	
	Mammals	
	Amphibians	
	Reptiles	
	Birds	

Note: EUNIS level 2 is shown here but other EUNIS levels can also be used where appropriate (Milestones 10 and 11).

4 Quantitative Models: A Spatially-explicit Modelling Framework

Biodiversity, EF, and ESS are closely linked and interwoven, and changes in one of these components may have a strong impact on the others (Gómez et al. 2017; Deliverable 3.2, Nogueira et al. 2016; Deliverable 5.1, Pletterbauer et al. 2016; Deliverable 4.1). To quantify such changes in a data-driven approach, the current state and causalities among biodiversity, EF and ESS needs to be assessed (Nogueira et al. 2016; Deliverable 5.1). In order to understand causal links between biodiversity, EF and ESS, as well as causal relationships between drivers, pressures and the impacted ecological components (biodiversity, EF, ESS), the use of a linkage framework has been proposed (Pletterbauer et al. 2016; Deliverable 4.1, chapter 1.2 and 3.4.1). Both of these relationships together can be used to balance the impact in terms of a sustainable EBM across future pathways (Gómez et al. 2017; Deliverable 3.2, chapters 2.4 and 2.5). Besides the linkage framework, such assessments require statistical and predictive models across space and time to allocate the impact and potential changes of each component (Figure 1). We highlight that within AQUACROSS, EBM is defined as "any management or policy options intended to restore, enhance and/or protect the resilience of an ecosystem" (Gomez D3.1, chapter 2.3; see also Box 5 "Ecosystem-based Management: one concept, several definitions" therein). With this in mind – and most importantly within the models – we do not distinguish at this stage between the different EBM definitions. Likewise, the IPBES "nature's contribution to people" (Diaz et al. 2018) definition is coherent to the AQUACROSS EBM definition, as viewed from a modelling perspective.

Biodiversity consists of several facets, such as taxonomic, functional or phylogenetic diversity (Jarzyna and Jetz 2016). While each provides a complementary view on biodiversity within a study area, the bottleneck for a comprehensive overview of the biodiversity status in a given case study area is often the availability of data. Species taxonomic data such as species occurrences at a site or within a watershed, is often most widely available compared to species-specific traits or phylogenetic data that can be used to approximate the biodiversity patterns (e.g., species richness and evenness). Assessments of the current state of biodiversity, as well as potential changes thereof under various scenario assumptions have been studied in freshwater and marine ecosystems across the globe (Martínez-López et al. 2014a; Martínez-López et al. 2014b). The aims of such analyses are manifold, ranging from exploratory analyses of biodiversity patterns (location of species hotspots) to analysing functional diversity, planning and managing conservation networks, and analysing biodiversity trends under e.g. climate and land use scenarios. Such analyses can be extended to functional diversity and, hence, to provide an in-depth view of the ecological processes within a defined case study area.

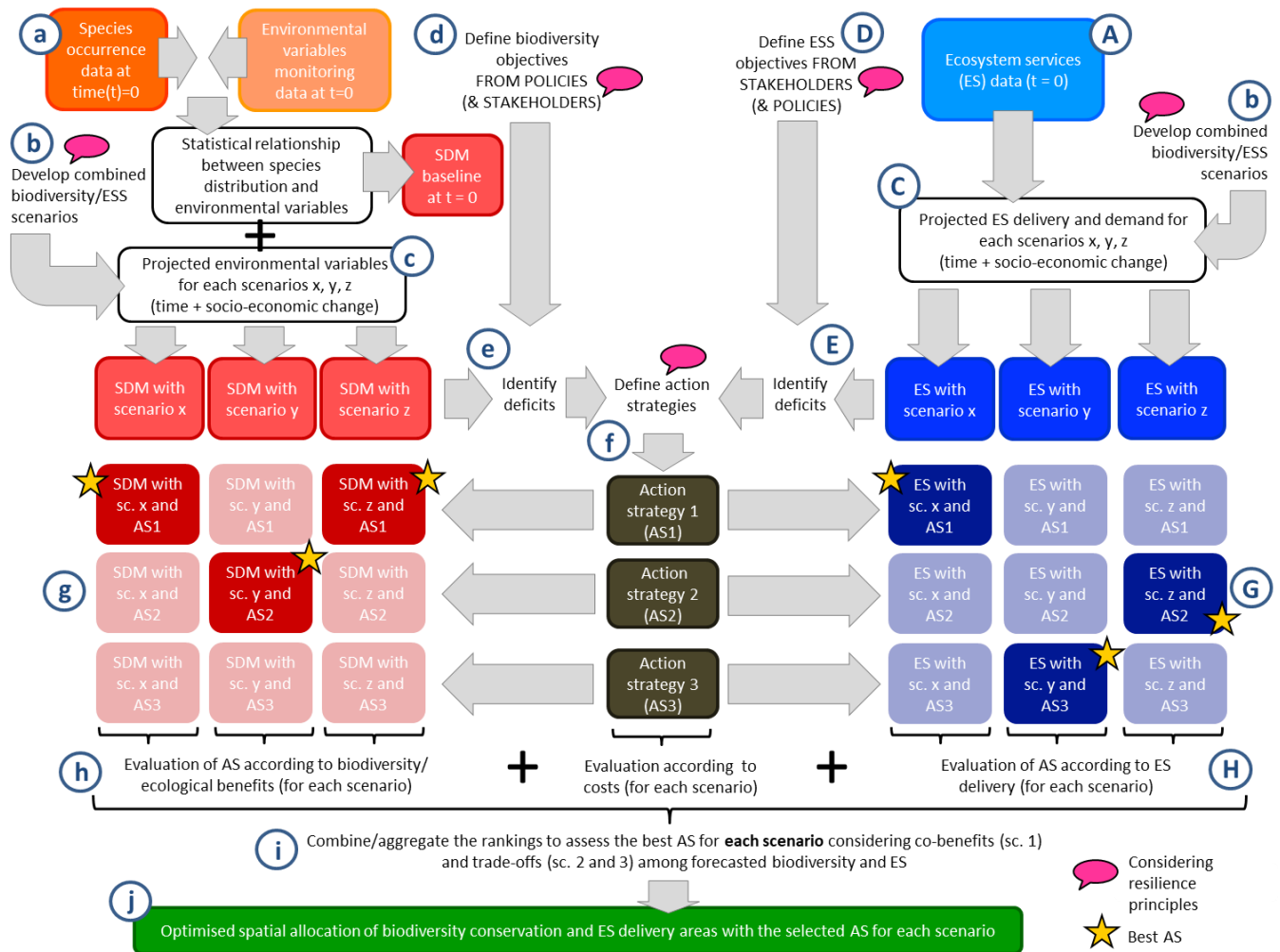


Figure 3: Workflow for evaluating action strategies and prioritising conservation and ecosystem services delivery areas for the application in the AQUACROSS case studies

Note: see Box 2 for a detailed description of the single modelling workflow components.

Source: Own elaboration

Box 2: A detailed description of the single components of the proposed spatial modelling workflow as shown in Figure 3

Different consecutive steps (a–i and A–I, respectively) include **(a)** establishing a statistical relationship among species occurrence data, e.g. from monitoring campaigns or existing databases, and respective information for environmental variables. This relationship is used to model the current ($t = 0$) species distribution. Environmental variables are projected according to scenarios (x , y and z ; defined by stakeholders **(b)**; scenario x being the baseline/business as usual scenario) and included in the statistical relationship to forecast species distribution for each of them **(c)**. Biodiversity objectives, i.e. targets, are identified according to respective policies **(d)**. Additional case–study specific biodiversity targets that are particularly important to stakeholders independent of policies may be included here. Deficits can now be identified for each scenario, by comparing projected species distributions with biodiversity targets **(e)**. Parallel processes, tailored to ESS, are conducted **(A–E)**. With the deficits for biodiversity and ESS laid out, a set of potential action strategies (AS) to reach biodiversity and ESS targets, are defined **(f)**. AS have to be chosen in a way not to jeopardise ecosystem resilience. Species distributions and ESS delivery for each scenario are modelled considering the expected environmental changes from each AS **(g)**. Predicted consequences of each AS for biodiversity and ESS in each scenario are assessed to identify the highest ranked AS for each scenario (marked with a yellow star) **(h/H)**. Biodiversity and ESS rankings and a third ranking of the costs of the individual AS are combined to find the optimal AS for each scenario **(i)**. Pre–cooked, spatially–explicit biodiversity and ESS data, derived from the best AS, are fed into *Marxan with Zones*. *Marxan with Zones* is a planning tool (not to confuse with a decision support system) that optimises the spatial allocation of biodiversity conservation and ESS delivery areas across the whole case study (e.g., a river basin, a basin plus an adjacent coastal zone, or a basin plus adjacent coastal and marine zones), while minimising cost and maximising targets for the management plan of a case study area **(j)**. These plans are discussed with the managers and potentially refined, to eventually support decision–making. See also Gómez et al. (2017; Deliverable 3.2, chapter 2.1.8) for further details.

ESS, and any changes thereof, are closely linked to biodiversity in aquatic ecosystems. Consequently, changes in biodiversity can impact ESS and EF, and ultimately the provision of ESS, also affecting human well–being (Gómez et al. 2017; Deliverable 3.2, Maes et al. 2012, Nogueira et al. 2016; Deliverable 5.1).

In the proposed modelling workflow, one key aspect is that BD, EF and ESS are assessed jointly to analyse and model the spatial patterns of management zones within a case study area. These components should be assessed together, to get an overview of how they might potentially change when viewed together, and how one could possibly mediate the other. Note that here BD is defined as above for practical reasons of data availability often limited to species diversity (Jarzyna and Jetz 2016) (while the CBD definition comprises many EF and ESS within BD). Only by accounting for this complementarity, the interaction between biodiversity, EF and ESS can be adequately analysed and used to predict potential changes and dependencies under alternative pathway scenarios, and to ultimately apply EBM within the case studies of AQUACROSS (Figure 3).

This chapter describes how BD, EF and ESS can be analysed jointly within a spatial framework, and how these can be linked within a spatially–explicit prioritisation process. The novelty in this approach lies in the simultaneous, spatial prioritisation assessment of biodiversity, EF and ESS within one workflow. Furthermore, it is a central aim to account for model uncertainties

and how they potentially cascade through the modelling framework (chapter 5). Specifically, we focus on a modelling workflow that combines SDM and ESS model outputs with the aim to spatially prioritise areas while accounting for these two key components. The document provides instructions and guidance to develop and apply such a framework on a given case study, and how to make decisions for each step. We highlight that a successful application of the modelling workflow is dependent on the data availability, and we therefore give recommendations and potential alternatives on how to proceed in data-deficient areas/regions (chapter 8). Ad-hoc practical guidance on the proposed spatial modelling framework will be made available for selected case studies.

In summary, the linkage framework (relationships and causal links) and the proposed modelling framework serve different purposes. The linkage framework can be used for qualitative analyses, to explore and understand a lesser-known system and to gain information on essential datasets that need to be obtained (and has been developed for each case study area within AQUACROSS, Milestone 11). The modelling framework can then build on this information, emphasising the essential linkages (given data availability) – it is a spatial data-driven approach, which does not rely on habitat types or classifications (as described in chapter 3), but uses spatial data layers that describe the habitat quantitatively.

4.1 Data requirements

The proposed framework enables a spatially-explicit workflow, and hence certain data requirements are essential to adequately depict the spatial allocation of biodiversity, ESS and finally the joint spatial prioritisation (chapter 4.1.1, 4.1.2 and 4.1.3, respectively). The different data types and specific requirements are further explained in the following sections.

4.1.1 Biodiversity component

For obtaining the potential range-wide distribution patterns of a given species, statistical models commonly known as SDMs are widely used (Elith and Leathwick 2009). These models relate species occurrences to the environmental conditions at those locations (such as climate, topography or land use). The model, built in environmental space, can then be projected onto the geographic surface to obtain the probability of occurrence of the species at a given location. Point-based models have a long tradition in ecology, where the occurrence of species is predicted for a number of sampling sites. With the increase of GIS techniques and available spatial data layers⁵, the range-wide application has become a central tool in understanding and predicting species habitat suitability across a large study area.

⁵ www.worldclim.org, (Hijmans et al. 2005); www.hydrosheds.org, (Lehner et al. 2008); www.earthenv.org/streams, (Domisch et al. 2015a); www.marspec.org, (Sbrocco and Barber 2013); see also Gómez et al. (2017; Deliverable 3.2, chapter 2.1.8)

For the modelling framework, such range-wide predictions across the study area are preferred for the following reasons: (i) Point data alone has the potential to be geographically biased and spatially non-representative, therefore potentially leading to biased diversity measures. For instance, easy-to-access sites are sampled more often than remote ones. SDMs first build the model in environmental space and then project onto geographic space, therefore potentially overcoming this obstacle by indicating the probability of occurrence not only at the sampling sites but within all spatial units; (ii) When it comes to sampling for species, the detection of species can be challenging, since in addition to observing and recording the “presence” of a given species, the non-detection (“absence”) strongly influences the observed occurrence pattern. When using models, carefully assessing the true positive and negative vs. the false positive and negative predictions in a confusion matrix (Pearson 2007) indicates the model skill, i.e. how well the model is able to discriminate between the presences and absences. The model therefore indicates where the environmental conditions for a given species could be suitable, but the species was not observed; (iii) Besides point occurrences, expert-range maps (e.g., from field guides) can help to infer the occurrence pattern of species (Domisch et al. 2016). While range maps are useful to deduct the “absence” of a species across a large study area, these maps, however, strongly overestimate the “presence” on fine spatial scales (i.e., indicating a “presence” within the entire expert range map which can have a considerable spatial inaccuracy (Hurlbert and Jetz 2007)).

In summary, modelled distributions provide a cost-effective way to assess the occurrence and diversity patterns of a wide array of species within an area of interest. SDMs are not free of caveats, and the data, models and outputs need to be used and assessed carefully (Domisch et al. 2015b).

In certain cases, the species data is not deemed suitable for modelling the distribution for various reasons, for instance: (i) there are not enough point records for creating a robust model (see Stockwell and Peterson (2002) for recommendations); (ii) the species point data is clumped/biased in environmental space, therefore leading to biased model predictions as well; (iii) or only weak statistical relationships between the response (species) and explanatory variables (environmental predictors) exist. Under such circumstances several alternatives could be applied that would allow using a “lighter version” of the modelling framework nonetheless (chapter 8).

The explanatory variables (i.e., spatial environmental layers such as temperature, land cover, etc.) for building the models ideally need to represent a similar spatial and temporal scale as the species data (Domisch et al. 2015b). For instance, if models are built on a catchment scale, then the variables need to be aggregated to this scale as well (e.g., average temperature, elevation range, or major land cover classes within each catchment) (Figure 2). This guarantees that the scale of observation of both response and explanatory variables are identical. For instance, fine-grain temperature data along a river reach should not be matched with a species observation somewhere within the entire catchment, but both need to be upscaled to the catchment as spatial units. Similarly, the time period of the environmental variables should match the time period of the species observations (e.g., species data from 2001–2006) should

not be matched with environmental data from 1980–1986 if the species has a longevity of a few years and no overlap between these time slices is given). For obtaining such data we refer to Gómez et al. (2017; Deliverable 3.2, chapter 2.1.8) for a selection of available data sources that provide first steps in building models.

In addition to the taxonomic diversity, functional diversity and traits can be used as well, and would provide another dimension of biodiversity within the prioritisation process. This could be achieved by using e.g. species traits/species functions within the ecosystem as a response variable to get a range-wide prediction across the study area. Alternatively, the SDM predictions can be linked to known traits and functions of each single species, with the aim to map the occurrence of a specific trait or function across the case study (Domisch et al. 2013, Kakouei et al. 2017, Kakouei et al. 2018).

4.1.2 Ecosystem services component

For computing spatial ESS layers, each ESS has specific data requirements that need to be met. Below, we provide a non-exhaustive list of possible spatially-explicit ESS layers that could be used within the proposed modelling workflow, as well as the basic data and spatial layers needed to create those. A comprehensive summary of each input data is beyond the scope of this report, and we refer to (Villa et al. 2014) for further information on how to compute such layers in practice.

- ▶ **Carbon sequestration (climate regulation) of wetlands and riparian areas**
 - Above-ground biomass based on vegetation maps or normalised difference vegetation index.
- ▶ **Flood prevention**
 - Presence and width of riparian areas and wetlands
 - Flood risk prone areas maps
 - Number of extreme precipitation events yearly
 - Distance to urban areas or agricultural fields
- ▶ **Erosion control and avalanche protection**
 - Soil erosion mitigation potential of vegetated areas
 - Slope
 - Soil type
 - Number of extreme precipitation events yearly
- ▶ **Freshwater biodiversity and genetic value**
 - Freshwater species richness
 - Number of freshwater rare species
 - Habitat suitability maps
- ▶ **Water use and regulation**
 - **Transactors:** dams and wells maps
 - **Supply:** Total annual surface water run-off (takes into account precipitation, evapo-transpiration and soil infiltration potential)

Use: maps of distance to:

- Populations weighted by population density (drinking water)
- Industrial areas (industrial water)
- Agricultural fields weighted by crop type (food provision and exports)

Regulation: precipitation variability maps

▶ **Water quality (nutrients retention)**

- Downstream distance to population areas and agricultural fields.
- Vegetation maps and biomass or land cover (wetlands).

▶ **Aesthetic, recreational and educational**

- Number of species
- Number of rare species
- Protection level
- Distance to urban areas weighted by population density (positive)
- Presence of industrial activities (negative)
- Presence of green areas
- Presence of water bodies (weighted by allowed activities) and ecological status
- Mountain peaks
- Presence of recreational infrastructures:
 - number and length of hiking paths
 - bird-watching facilities
 - number of environmental education facilities
- Presence of religious sites
- Number of visitors (expenses, duration)

▶ **Pollination**

- Number of wetlands
- Presence/Abundance of pollinators
- Distance to agricultural fields that can be pollinated
- Percentage of agricultural fields within a given distance around the wetland (must be crop types that need/benefit from pollination)

4.1.3 Spatial prioritisation

We propose the software Marxan with Zones (Watts et al. 2009) to be used to identify priority areas for the conservation of freshwater biodiversity and different ESS related to marine, coastal and freshwater ecosystems. These ESS under consideration will cover different types, including services that are compatible with conservation of biodiversity (e.g., regulation and/or cultural services) and services which might entail risks to the conservation of biodiversity and/or other services (e.g., provisioning services). This will be done to demonstrate how to maximise co-benefits between the maintenance of some ESS and conservation of biodiversity (e.g., there could be benefits for biodiversity conservation by promoting flood regulation) while minimising potential trade-offs (e.g., reducing potential negative effects of granting access to provisioning services on conservation of biodiversity and the maintenance of other ESS as much as possible).

With this aim, the spatial allocation of different management zones will be spatially prioritised. These different management zones will include i) only conservation and compatible ESS zone (co-benefits zone) and ii) a zone for accessing provisioning services (trade-off zone).

The prioritisation builds on the outputs of the biodiversity and ESS components within each spatial unit. Hence, no new input data is created in this step and we point to chapter 4.3.2 and 6 of this document to describe the integration of biodiversity and ESS within the prioritisation framework.

4.2 Data structure and spatial units

Each realm – marine, freshwater or coastal – comes with its own spatial structures and units how species and communities are sampled and how spatial units are subdivided in geographic space. Ideally, the spatial units for all three model components (biodiversity, ESS, spatial prioritisation) should be identical throughout the workflow to match the biodiversity and ESS representativeness in the spatial prioritisation process.

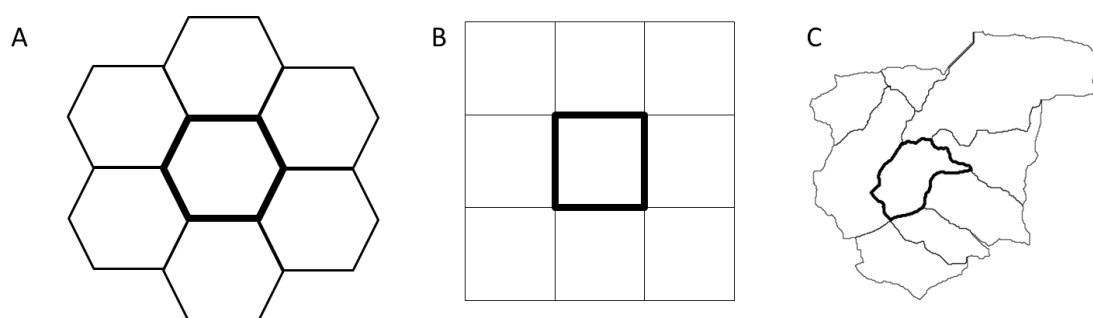


Figure 4: Schematic overview of spatial units for the modelling workflow

Note: Hexagons and grids (A–B) in the marine and coastal (and terrestrial) realm, (C) sub-catchments (polygons) in the freshwater realm. The outline of the centre unit (bold line) illustrates the connectivity and spatial dependency among neighbouring units that is essential in Marxan when creating spatially prioritised networks.

Source: Own elaboration

In the marine realm, the spatial scale of analysis can be adjusted by simply rescaling the size of hexagons and grids, respectively. This usually depends on the spatial grain of the available species and environmental data. In general, hexagons are preferred due to the connectivity of neighbouring spatial units. A hexagon shares a boundary line with six units into all directions, whereas a grid shares a line with four neighbours. This has important implications for the spatial prioritisation, since the overall boundary length of those spatial units that build a reserve network is a crucial factor for the optimisation algorithm.

However if the target data (e.g., species distribution) comes readily aggregated in grids (e.g., atlas or checklist data), these units are typically used without re-adjusting the data. To adequately account for freshwater biodiversity, as well as freshwater-relevant ESS, watersheds are considered the optimal solution for spatial units in this realm. Here, the spatial scale is accounted by the hierarchical nestedness of the basins and sub-catchments and deserves the identification of the most favourable scale given the prioritisation targets (i.e., depending on the scale the data is available).

In coastal regions, the transition between freshwater and marine realms can be achieved by a seamless boundary of sub-catchments, and hexagons or grids. While the biodiversity models for marine and freshwater species are run independently, their outputs can be used jointly in one spatial prioritization analysis.

The spatial and temporal scale of analysis as well as the size of the spatial units is also directly linked to the uncertainties within the single models, and has the potential to vary within the modelling workflow (Gómez et al. 2017; Deliverable 3.2, chapter 2.1.8). If too broad, the model uses data across a wide spatial and temporal range (e.g., many land cover types aggregated within on spatial unit, or many years of species samplings linked to a certain habitat characteristic such as temperature), and limits the discriminative abilities of the model to predict the response variable adequately. In contrast, the spatial units should not be smaller than the minimum scale of observation or size of the sampling plot.

4.3 Model components and types

For each of the three components of the modelling workflow, there are several options and model types that can be applied depending on the data availability and quality. The following chapter provides an overview of such options for biodiversity models (chapter 4.3.1), EF and ESS models (4.3.2) and spatial prioritisation (4.3.3).

4.3.1 Biodiversity models

The variety of statistical Species Distribution Models

Several types of SDMs can be used to obtain range-wide predictions of species habitat suitability across the study area, for instance single algorithms (Phillips et al. 2006), an ensemble framework (Thuiller et al. 2009), an iterative ensemble model (Lauzeral et al. 2015),

applying SDMs in a Bayesian framework (Latimer et al. 2006) and using joint SDMs (Pollock et al. 2014). While each method provides the habitat suitability map (which is key for the subsequent spatial prioritisation procedure), each also comes with advantages and limitations that need to be carefully assessed and balanced beforehand. The following chapter briefly introduces each type and points to material that provides further information.

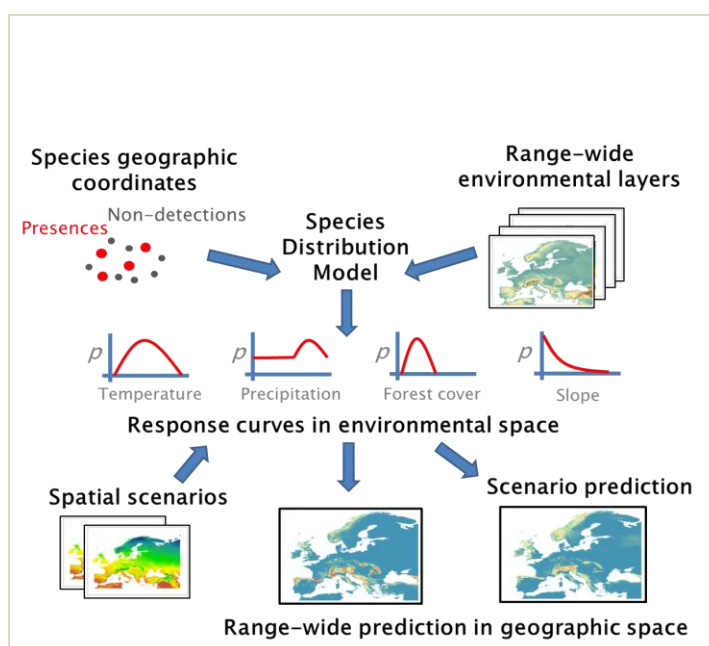
Applying **single modelling algorithms**, such as a Generalized Linear Models, Random Forest (Breiman 2001) or Maximum Entropy (Phillips et al. 2006), forms the core of the SDM literature (Elith and Leathwick 2009). While the advantage of a single algorithm is that it is easy to handle and to understand how the final prediction is derived, it is important to bear in mind that each algorithm class (regression, classification, machine learning) builds the statistical model (in environmental space) in a different way. The consequence is that it might be difficult to judge whether this particular algorithm provides the best result given the data (Qiao et al. 2015), even though the model skill in terms of evaluation and validation results might be acceptable. Using single algorithms is of advantage when the focus is on understanding species–environment dependencies, i.e. when the model should provide information on species’ ecological preferences, rather than the best–case mapped prediction.

The caveats of using single algorithms is reduced when using an **ensemble modelling framework** (Thuiller et al. 2009). Here, several single algorithms yield a prediction, which are then combined and provide an ensemble or consensus prediction. This consensus is achieved by, for instance, giving more weights to algorithms that have a high relative model evaluation score. The advantage is that the mapped prediction can be considered to be more robust as this method takes the inter–model variability into account (i.e., algorithm–derived uncertainty). However understanding the species–environment relationship can be difficult because of the weighting scheme of various statistical relationships and methods.

Figure 5: Schematic workflow of species distribution models

Note: Species geographic coordinates and range–wide environmental predictors are used to build a model in environmental space, yielding response curves indicating the probability of occurrence under the environmental gradient for each variable. This model can then be projected in geographic space, providing a range–wide prediction across the case study area. Once the model has been built, a set of spatial scenario layers can be used to assess changes in species distributions.

Source: Own elaboration



Iterative ensemble models (Lauzeral et al. 2015) are an extension of ensemble models, and have been developed to overcome the issue of noisy absences. Noisy absences are considered species absences that, however, might be considered presences due to lacking non-detection during the sampling. Iterative ensemble models use the “raw” species occurrence data, and replace the original absences to presences, in case the model predicts a high probability of occurrence at those locations. This new set of occurrences is then used for a new model run, and this procedure is iterated until the predictions are stabilised. Iterative ensemble models have shown to outperform ensemble models, however they are also more time consuming, depending on the stabilisation of the predictions (i.e., the degree of noise in the original absences). As each iteration is dependent on the previous one, no parallelisation is possible.

Hierarchical models (multilevel models) are a generalisation of linear and generalised linear models. The regression coefficients are themselves given a model, the parameters for which are then estimated from the data (Gelman 2006). Such hierarchical models are very flexible and allow adding several levels (such as random effects and autoregressive model terms) within the model, and if in a Bayesian framework, also yield the uncertainties from Markov Chain Monte Carlo derived samples from the posterior probability distribution. In addition to the average prediction (comparable to the maximum likelihood outputs), the lower 2.5 and upper 97.5 credible intervals show where the model skill to predict the occurrence (or the species–environment relationship) is uncertain. Different types of SDM-specific hierarchical models are:

- ▶ **Hierarchical Bayesian SDMs:** Running a SDM in a Bayesian framework requires sound presence–absence species data stemming from surveys to fulfil the closure assumption (if a site was visited multiple times and the species was observed at least once, the environment is assumed to be suitable for the species and any non-detections during other visits are due to imperfect detections (Royle et al. 2005). These models consist, for instance, of a suitability model (species–environment relationship) and observability model (species detectability), and an autoregressive term to account for spatial random effects (accounting for processes not captured by the variables used in the model).
- ▶ **Hierarchical Bayesian joint-SDMs:** Joint species distribution models describe the community of species as a whole instead of using separate models for each species (Ovaskainen and Soininen 2011, Pollock et al. 2014, Warton et al. 2015). This can be done by assuming that the species specific parameters are drawn from a joint distribution for the whole community. With joint models it is possible to include rare species and to better represent community characteristics like richness.

As described above, species range-wide spatial predictions can be linked with their traits, e.g. using the freshwaterecology.info database (Schmidt–Kloiber and Hering 2015). This adds another dimension of biodiversity within the case study area and can give a more detailed view within the spatial prioritisation process.

SDMs are widely used to predict changes in biodiversity under various scenarios, such as under climate, land use or management scenarios (Figure 5). Here the model, once established under the baseline environmental conditions, uses spatial scenario data such as future temperature or precipitation. Note that the model can only use those variables that were also used to build

the model. Scenarios can be projected on the same case study area, a different case study area, or on a different time period, or a combination.

Criteria to select the Species Distribution Model method

The selection of the modelling method strongly depends on the aim of the modelling exercise, the species data availability, data type, spatial units, study area, model complexity and computation power and time, as well as the combination of these components. Below, we provide a non-exhaustive checklist of key assumptions and guidelines on how to choose. For more details, refer to (Elith and Leathwick 2009) and (Hijmans and Elith 2013).

- 1 Define the aims and goals of the modelling exercise.** Understanding relationships, causal links and communicating the results to the public requires a different model, of which the sole purpose is a mapped distribution of the species.
- 2 Environmental and spatial representativeness of the data.** For fitting SDMs, species data needs to be spatially well represented (avoid geographically-biased data and consider thinning options if needed (Boria et al. 2014)). The environmental layers should exceed the coverage of the species points to ensure an environmental gradient within the case study area, exceeding that of the species point locations.
- 3 Spatial units and study area.** The spatial units define the fine or coarse representation of the species distribution within the case study area. Most importantly, spatial grain (e.g., 1 km) of the sampled species point data, and the environmental layers should match. It is possible to aggregate fine-grain data to coarser units (e.g., 1 km to 5 km), but the opposite is more challenging and should be assessed with care (e.g., downscaling 5 km environmental layers to 100 m does not create any new data, but may introduce a large amount of uncertainties when fitted to fine-scale species data). Regarding the modelling framework, the spatial units in the SDMs should be identical to those in the ESS and Marxan models.
- 4 Species data** can consist of presence-only, presence-absence, abundance data or survey data with repeated visits. The type of the species occurrence data is an important model selection criterion, and defines the subsequent model type that can be used. Abundance and survey data with repeated visits includes more information on presence-absence or presence-only data, and hence a more complicated model with assumptions on e.g. species detectability can be considered.
- 5 Model complexity.** Directly linked to the previous species data, which defines the possible degree of model complexity, number of parameters and hierarchical levels.
- 6 Computation efficiency/time demand.** Although in general not of major importance nowadays due to the availability of high-performance computers or access to computer clusters, the combination of the number of spatial units and the size of the study area. Nonetheless, the number of species to be used in the models and the model complexity can limit the feasibility of the modelling approach. A test on a smaller area and with one species enables to upscale the resources needed and to identify the possible bottleneck. A

useful approach could be the use of a virtual species with a defined environmental preference for testing purposes (Qiao et al. 2015). This would enable to focus on the modelling method, as the environmental envelope the species inhabits is defined a priori (see e.g., the “virtuallspecies” (Leroy et al. 2016) or “SDMvspecies” (Duan et al. 2015) packages in R, or the stand-alone software “Niche Analyst” in (Qiao et al. 2016)).

Tools for building statistical SDMs

There are a number of tools for building statistical SDMs, both stand-alone software (Table 3) and within the platform “R” (R Core Development Team 2017). Regarding data retrieval and quality checks, the “MODESTR” software⁶ (García-Roselló et al. (2013) could be of interest when preparing species occurrence data.

Table 3: Stand-alone software for building Species Distribution Models

Name	Web link	Reference
Maxent	https://biodiversityinformatics.amnh.org/open_source/maxent/	Phillips et al. (2006)
Niche Analyst	http://nichea.sourceforge.net/	Qiao et al. (2016)
ENMTools	http://enmtools.blogspot.de/	Warren et al. (2010)
biomapper	http://www2.unil.ch/biomapper/	Hirzel et al. (2002)
openModeller	http://openmodeller.sourceforge.net/	de Souza Muñoz et al. (2011)
MoDEco	http://faculty.ucmerced.edu/qguo/software/modeco/modeco.html	Guo and Liu (2010)
GARP	http://www.nhm.ku.edu/desktopgarp/	Scachetti-Pereira (2002)

Stand-alone programs are easy to use and provide a graphical user-interface, however, they are not usually intended to be used for batch-processing a number of species with simultaneously automating subsequent analyses. Here, the open-source platform “R” (R Core Development Team 2017) is increasingly used for building SDMs (Hijmans and Elith 2013), maximising flexibility regarding the selection of desired models and analyses (i.e., using any custom-written script using available libraries).

In addition, a number of SDM-oriented libraries that eliminate the burden of programming functions for data preparation and analyses do exist, such as “maxnet” (Phillips et al. 2017) and “dismo” (Hijmans et al. 2017) for single-algorithm models, “sdm”⁷ (Naimi and Araújo (2016) and “biomod2” (Thuiller et al. 2009) for ensemble forecasts, “demoniche” for simulating spatially-explicit population dynamics (Nenzén et al. 2012), “ecospat” (Di Cola et al. 2017) to support spatial analyses and distribution models, and “usdm” for assessing uncertainties in

⁶ <http://www.ipez.es/ModestR>

⁷ <http://www.biogeoinformatics.org/>

models (Naimi 2015). Fitting Bayesian models can be achieved using software packages like Stan (Stan Development Team 2016) and Jags (Plummer et al. 2016), which provide an interface to implement such models with the statistical computing software R (R Core Development Team 2017) and do Bayesian Inference. Also, the “hSDM” package (Vieilledent et al. 2014) provides a fast and effective method to run SDMs in a Bayesian framework.

4.3.2 Ecosystem service models

Introduction on mapping and modelling ESS

ESS assessment tools are aimed to connect ESS to beneficiaries, rather than simply quantifying ecological processes and functions or natural resources. Several ESS assessment tools are increasingly improving the accounting of non-monetary nature-based flows to society by means of addressing a very interdisciplinary research field.

Thus, ESS mapping has achieved rapid progress in a very short time frame. To our knowledge, the first peer-review ESS maps were published in 1996 and, since then, a large number of ad hoc mapping studies have been conducted. This significant progress corresponds to advances in computing power, modelling and geographic information systems (GIS) as well. There is a variety of ESS (i.e., participatory mapping) and biophysical modelling approaches based on the consensus that ESS maps should provide a direct connection between ecological processes at landscape scale and policy making. Here, the direct use and aggregation of participatory mapping and use of such spatial data enables a fast and cost-efficient way to address the demand of ESS, such as the outdoor recreation use by people as shown by van Zanten et al. (2016) and Komossa et al. (2018) across Europe based on Panoramio, Flickr, or Instagram social media services. Such information are extremely valuable, however bear the risk of biases, where, for instance, certain countries are underrepresented, or simply due to technical constraints of contributing georeferenced information to a wider database. So far the most readily available data to consider ESS demands are population density maps.

Over the past years, ESS mapping tools gave the way towards more modelling-oriented tools to overcome such biases. ESS models are computational representations of the environment that allow biophysical, ecological, and/or socio-economic characteristics to be quantified and explored. Modelling approaches differ from mapping approaches as (i) they are not forcibly spatial (although many models do produce spatial outputs); (ii) they focus on understanding and quantifying the interactions between different components of social and/or environmental systems; and (iii) they are capable of exploring both alternative scenarios and internal model dynamics by changing forcing inputs of the models.

When applied to the assessment of ESS, models are important tools that can quantify the relationships that underpin ESS supply, demand, and flows and, in some cases, produce maps representing these factors (Martínez-López et al. 2015). Furthermore, as models can explore scenarios, trade-offs that result from different scenarios can be assessed as well (Balbi et al. 2015, Martínez-Fernández et al. 2014). Modelling is now being widely applied in the field of ESS. There are a large number of modelling approaches and a wide range of existing models

that can be used for ESS assessment (see details for a selection of 20 ESS models below). Modelling has considerable potential to evaluate both the ecosystem structure and function underlying ESS and the supply and demand for ESS themselves. Further, modelling provides the potential to explore the impacts of environmental change and management on the future provision of ESS through scenarios, making them vital tools for ESS decision.

By means of integrated modelling tools, ESS mapping can be studied in combination with other ecological and socio–economical interactions that might exert pressures on ecosystems. All the elements from the DPSIR framework can be linked with the mapping and evaluation of ESS by means of integrated modelling tools, in order to enable EBM approaches (Niemeijer and de Groot 2008).

The interdisciplinarity required for the study of ESS is best tackled using integrated modelling tools that are able to represent the wide variety of interactions that happen within socio–ecological systems, such as those based on behaviour, market prices, local versus global economy, etc. Moreover, in view of the ongoing climate change, there is certainly an urgent need to integrate the different elements that compose socio–ecological systems (processes, agents, events, etc.) in order to enhance governance, understand indirect and nonlinear causal links, and be able to predict future scenarios (Villa et al. 2017).

This chapter provides a basic overview of different types of tools that have been applied to ESS assessments and discusses the main features from a modelling perspective (Burkhard and Maes 2017, Christin et al. 2016).

Availability of mapping tools

Numerous “EBM tools” exist⁸, however, most of them are ecological, hydrologic, or other biophysical process models that lack an explicit focus on ESS. We selected 20 tools specifically considering their ability to represent more than one service in more than one particular case study, so that selected tools would be able to quantify and/or monetise multiple services, sometimes over time and across landscapes. In the following, they are briefly described according to their online documentation, in alphabetical order:

- 1 *ARIES, Artificial Intelligence for Ecosystem Services*⁹ (Basque Centre for Climate Change, BC3): A cyber–infrastructure to integrate multiple modelling paradigms for spatio–temporal modelling and mapping of ESS. Supports artificial intelligence features (semantics and machine learning) for model selection and assemblage to quantify ESS flows from ecosystems to beneficiaries (Villa et al. (2014). The models developed with ARIES, used by three case studies in this project, provide the advantage of clearly presenting the service flow as ecosystem potential on the one hand, and the service demand on the other hand, where the latter is mainly based on population density maps. Ecosystem potential and demand together generate the relative service. Also, participatory elicitation of spatially

⁸ <https://ebmtoolsdatabase.org/tools>

⁹ <http://aries.integratedmodelling.org/>

explicit criteria can be done to represent different stakeholder groups by means of spatial multiple criteria analysis (SMCA; Villa et al. 2002).

- 2 *Benefits of SuDS Tool*¹⁰(CIRIA): A Microsoft Excel extension to provide guidance to help practitioners estimate the benefits of Sustainable Urban Drainage Systems (SuDS). Estimates are based on overall drainage system performance without the need for full-scale economic inputs. It uses ESS to understand the overall benefits that SuDS provide over conventional piped drainage.
- 3 *CLIMSAVE IAP*¹¹(Climasave project consortium): A regional integrated assessment web-based model that provides options for ESS assessment at a European scale. It is based on an integrated system of models for a number of different sectors including urban growth, freshwater, coastal/fluvial flooding, biodiversity, agriculture, and forestry. A wide selection of climate scenarios is included within the system as well as four stakeholder-defined socio-economic scenarios (Harrison et al. (2013)).
- 4 *Co\$ting Nature*¹² (King's College London and AmbioTEK): Mapping and modelling tool for multiple ESS using global datasets. Quantifies ESS as opportunity costs (i.e., avoided cost of producing those services from a non-natural capital substitute) (Mulligan (2015)).
- 5 *EcoMetrix*¹³ (EcoMetrix Solutions Group and Parametrix): Field-based tool designed for use at relatively fine spatial scales. Primary use is to illustrate the effects of human activities (i.e., development or restoration scenarios) on ESS.
- 6 *EnSym, Environmental Systems Modelling Platform*¹⁴ (State of Victoria, Australia): Environmental systems modelling platform for researchers to apply process-based models. Designed to provide information on how and where to invest to maximise environmental outcomes (Ha et al. (2010)).
- 7 *Envision*¹⁵ (Oregon State University): GIS-based tool for scenario-based planning and environmental assessment. Enables "multi-agent modelling" to represent human decisions on landscape simulations (Guzy et al. (2008)).
- 8 *ESR for IA, Ecosystem Services Review for Impact Assessment*¹⁶ (World Resources Institute): Method to address project impacts and dependencies on ESS within the environmental and social impact assessment process. It identifies measures to mitigate project impacts on benefits provided by ecosystems and to manage operational dependency on ecosystems (Landsberg et al. (2011)).
- 9 *ESTIMAP* (EU JRC): A collection of spatially explicit model approaches and indicators that assess potential supply and demand of ESS. It is implemented within a GIS and is designed

¹⁰ <http://www.susdrain.org/resources/best.html>

¹¹ <http://www.climsave.eu>

¹² <http://www.policysupport.org/costingnature>

¹³ <http://www.ecometrixsolutions.com/ecometrix.html>

¹⁴ <https://ensym.dse.vic.gov.au/cms/>

¹⁵ <http://envision.bioe.orst.edu/>

¹⁶ <http://www.wri.org/publication/ecosystem-services-review-impact-assessment>

to be a standardised, replicable system developed for use in the European Union. It uses different methodologies for each ESS (Zulian et al. (2014)).

- 10 *EVT, Ecosystem Valuation Toolkit*¹⁷ (Earth Economics): Provides monetary values for natural assets under multiple modules. Includes a Researcher's Library, searchable database of ESS values, and SERVES, a web-based tool for calculating ecosystem service values.
- 11 *IMAGE*¹⁸ (PBL Netherlands Environmental Assessment Agency): An ecological-environmental model framework that simulates the environmental consequences of human activities worldwide. It represents interactions between society, the biosphere and the climate system to assess sustainability issues such as climate change, biodiversity and human well-being. The objective of the IMAGE model is to explore the long-term dynamics and impacts of global changes that result from interacting socio-economic and environmental factors. Has an ESS dedicated component (Stehfest et al. (2014)).
- 12 *InVEST, Integrated Valuation of Ecosystem Services and Tradeoffs*¹⁹ (Natural Capital Project, Stanford University): Spatial mapping and modelling of multiple ESS. Includes a diverse set of provisioning, regulating, and cultural services from marine and terrestrial environments. The models primarily provide results in biophysical terms to which valuation can be applied (Tallis et al. (2013)).
- 13 *i-Tree Eco*²⁰ (US Forest Service): A software application designed for urban forest assessment. It uses field data from complete inventories or randomly located plots, along with hourly air pollution and meteorological data. It quantifies the structure and environmental effects of urban forests (or trees) and calculates their value to communities.
- 14 *LUCI, Land Utilisation and Capability Indicator*²¹ (Victoria University of Wellington): Explores the capability of a landscape to provide a variety of ESS. It compares the services provided by the current use of the landscape and its potential capability. The model uses this information to identify areas where change or maintenance of current conditions may be most beneficial (Jackson et al. (2013)).
- 15 *MapNat App*²² (UFZ): A smartphone application (mapping nature's services) designed as a tool for citizens and/or scientific research to map nature's services, which the person mapping them is currently using or studying, including the location where they are used or studied. The records are sent from a mobile device to a server, which collects and processes the records of all users. Opening the map view of MapNat, users are enabled to identify spots or regions providing nature's services they may be interested in, which have been mapped by other users.

¹⁷ <http://esvaluation.org/>

¹⁸ http://themasites.pbl.nl/models/image/index.php/Welcome_to_IMAGE_3.0_Documentation

¹⁹ <http://www.naturalcapitalproject.org/>

²⁰ <http://www.itreetools.org/>

²¹ <http://www.lucitools.org/>

²² <http://www.ufz.de/index.php?en=40618>

- 16 *MIMES, Multiscale Integrated Models of Ecosystem Services*²³ (Affordable Futures): Modelling platform designed to quantify causal linkages between ecosystems and the economy. MIMES allows an individual to map decisions/policies, and the output illustrates how those choices affect the economy and ecosystems (Boumans et al. (2015)).
- 17 *NAIS, Natural Assets Information System*²⁴ (Spatial Informatics Group): Integrated valuation database and reporting engine. The database is integrated with proprietary spatial modelling tools to characterise ecosystems and flow of services on the landscape (Troy and Wilson (2006)).
- 18 *SENCE, Spatial Evidence for Natural Capital Evaluation*²⁵ (Environment Systems): Provides information to support evidence-based decision making on ESS. It is based on the idea that any area of land is capable of contributing to one or more ESS. That capability is based on factors including habitat, soil and geology, landform and hydrology, how land is managed and how it is culturally understood.
- 19 *SolVES, Social Values for Ecosystem Services*²⁶ (U.S. Geological Survey, USGS.) Spatial mapping and modelling tool primarily for quantifying cultural ESS using public participatory GIS (Sherrouse et al. (2011)).
- 20 *TESSA, Toolkit for Ecosystem Service Site-based Assessment*²⁷ (BirdLife International): A process using flow charts to describe how ESS benefit society under current conditions and alternative scenarios (Peh et al. (2013)).

We used 14 criteria related to five aspects in order to summarise the features of the selected tools (Table 4). The relative importance among those criteria will vary according to the specific community of users: modellers, stakeholders and/or practitioners. A summary of the features of each tool can be found in Table 4.

²³ <http://www.affordablefutures.com/orientation-to-what-we-do/services/mimes>

²⁴ <http://www.sig-gis.com/services/ecosystem-services/>

²⁵ www.envsys.co.uk/sence/

²⁶ <http://solves.cr.usgs.gov/>

²⁷ <http://tessa.tools/>

Table 4: List of criteria used for assessing various criteria of ecosystem service models from a user's perspective

	Criteria	Description
Implementation	Web-based tool	A piece of software running online.
	Spreadsheet extension	The ability to read and write excel/tabular files.
	Stand-alone software	Whether it needs to be used in combination with other piece of software.
	Open-source	Whether the source code of the software is open and it is free for users.
Data related capabilities	Pre-loaded data	Containing already useful data for analysis.
	User's data	The ability to input your own data.
Model related capabilities	Pre-loaded models	Containing ready to run models.
	User's models	The ability to create your own models.
	Modelling integration capacity	The ability to easily connect different models.
Spatial scale appropriateness	Local-scale	Whether models at local scale can be built.
	Regional-scale	Whether models at regional scale can be built.
	Global-scale	Whether models at global scale can be built.
Spatial and temporal explicitness	Mapping	Whether spatial assessments can be done.
	Dynamic modelling	Whether dynamic/temporal models can be built.

Table 5: Summary of the ecosystem service tools' features

Tool ID	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
Web-based tool	✓		✓	✓	✓					✓			✓		✓					
Spreadsheet extension		✓						✓		✓							✓			✓
Stand-alone software	✓				✓	✓	✓				✓	✓	✓					✓		
Open-source	✓						✓					✓								n/a
Pre-loaded data	✓			✓		✓	✓			✓	✓						✓			
User's data	✓	✓			✓	✓	✓		✓			✓	✓		✓	✓		✓	✓	✓
Pre-loaded models	✓	✓	✓	✓	✓	✓	✓		✓		✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
User's models	✓						✓									✓				
Model integration	✓		✓			✓	✓							✓		✓				
Local-scale	✓	✓			✓	✓	✓	✓	✓	✓		✓	✓	✓	✓	✓	✓	✓	✓	✓
Regional-scale	✓		✓			✓	✓	✓	✓	✓		✓	✓	✓	✓	✓	✓	✓	✓	✓
Global-scale	✓			✓		✓	✓			✓	✓	✓		✓		✓	✓	✓	✓	
Mapping	✓		✓	✓	✓	✓	✓		✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
Dynamic modelling	✓		✓			✓	✓									✓				

Note: Tool IDs (columns) correspond to the numbering in “Availability of mapping tools” in the chapter section above; the single criteria (rows) correspond to Table 4.

Criteria to select ESS tools: a modeller perspective

In this section, we describe a non-exhaustive set of key criteria that we think could play a crucial role from the modelling perspective in assessing ESS mapping and modelling tools. In addition, we try to understand what the relative importance among those criteria is according to a community of stakeholders and practitioners. From a modelling perspective, we suggest that key criteria for considering an ESS tool are:

- 1 **Modelling integration capacity:** ESS are processes happening within complex systems, known as social-ecological systems or coupled human-natural systems, where human and natural components interact at multiple spatial and temporal scales. Models of complex

systems should be capable of capturing such complexity through appropriate methods. It is also increasingly clear that the dominant “one model fits all” paradigm is often ill-suited to address the diversity of real-world management situations that exist across the broad spectrum of coupled natural-human systems and more so when it comes to multiple ESS in different geographical contexts and conditions of data availability. Methods are necessary that can integrate different modelling techniques and types of knowledge, including multiple quantitative and semi-quantitative data sources and expert opinion.

Indeed, having access to multiple methods and breaking down complex systems into more treatable building blocks that talk to each other is the only viable option. Ideally, a modelling platform that is capable of capturing complexity should therefore make use of different modelling paradigms including system dynamics, agent-based models, Bayesian networks, GIS algorithms, analytical models, look-up tables, and multi-criteria analyses.

- 2 **Spatio-temporal scale flexibility:** ESS change according to the system at stake and the perspectives of the beneficiaries at stake. A powerful modelling platform should allow a flexible definition of the system boundaries (e.g., the context in terms of space and time) and of the main elements under analysis. Customised models should therefore quickly adapt to the selected context and produce context dependent results.
- 3 **ESS comprehensiveness:** ESS encompass biophysical, ecological and socio-economic dimensions through dynamic processes of very different nature. Many categorisations are available in the literature. Here we just highlight the very different dynamics of provisioning, regulating, and cultural services and even among services of the same category. For example, food provision and water provision display very different modelling requirements one more related to biomass dynamics and the other more related to hydrology. This multifaceted and multi-domain area of research requires different models that can be offered by one or more tools, but in different ways according to the specific service.
- 4 **Re-usability and customisation:** Too often models are standing monoliths developed for the purpose of one specific case study and are scarcely generalisable. This is very demanding for the individual modeller in terms of efforts put into model development from scratch, but it is also an inefficient workflow of knowledge generation from a collective point of view. On the contrary reusability and integration of data artifacts and models are becoming increasingly fundamental in interdisciplinary science (Dubois et al. 2016). For example, reusability, versatility, reproducibility, extensibility, availability and interpretability were identified as requirements for sustainability science knowledge structuring (Kumazawa et al. 2009). Modern ESS assessment tools should aim at supporting a workflow where multi-domain models of ESS processes are customised to specific cases with users being provided specific knowledge.
- 5 **Network of users:** In the era of social networks and socially crowded information, a modern ESS tool should build on the network of its users. First, because community-driven knowledge generation and vetting has proven to be a very powerful strategy for advancing knowledge availability (e.g., see the development of Wikipedia over the last years). Second,

because ESS assessment tools transcend the typical producer–user relation in the software industry. Users are the ultimate depository of local knowledge and they should be able to make their knowledge available. This can greatly improve the quality of the assessments. Modern tools should therefore promote community ownership rather than proprietary interests. Part of this depends on the software development philosophy, which goes beyond making the software openly accessible.

- 6 Type of output and interpretation:** ESS can be quantified in many ways— such as biophysical units, monetary values, or relative rankings in expert–based estimations or cultural ESS assessments. For this issue, the user selects whether desired outputs are monetary, biophysical, recreational or cultural metrics, and whether spatial and/or temporal outputs are needed.

When dealing with models, it is important to remember that they (i) are human–made constructs, (ii) are just one way of accessing information on the environment, and (iii) need to be considered in the context for which they were developed. It is easy to envision situations where decision makers are led to the wrong conclusions if model outputs are taken as indisputable proof without understanding how well model outputs represent the environmental issue in question, or because a modeller has applied a pre–existing model to a new situation without customising it to meet local conditions.

The ESS concept is designed to raise decision–maker awareness of the benefits offered by nature. This decision–maker focus means that ESS model developers need to be keenly aware of the implications of how their models are used. Maps, flow charts, info graphics, tabular summaries, and trade–off and scenario analyses can provide managers and decision makers with the key information to better consider nature’s benefits in resource planning decisions. The information should be provided in the simplest and clearest possible way avoiding pre–packaged silver bullet recommendations.

- 7 Treatment of values:** How much are ESS worth? This is a key question in studies of ESS— and can be a very loaded question. Modelling studies are often capable of producing quantified outputs of ESS (or their proxies) in biophysical (e.g., forest stock as ton C ha^{-1}) and monetary units (e.g., sale price of timber in £/\$/€). However, value is a much more elusive concept, particularly when weighing disparate services against one another. Questions such as “value for whom?” and “value as of when?” need to be considered by both modellers and those who use the outputs of models. This is because values are manifold; they are not static and they vary depending on which groups place a value on ESS. However, models, particularly deterministic ones producing single outputs, do not usually reflect these issues. This is particularly problematic for cultural services, which are very much socially determined, but even provisioning and regulating services will have different values in different social contexts in response to changing environmental, socio–economic or political factors such as a changing climate, political tensions, trade bans or new supply opportunities.

Another issue is that value, in economic terms, is a marginal notion. The types of marginal values most common to economic analysis are those associated with unit changes of

resources. On the contrary, most ESS assessment exercises focus on the value of a certain ecosystem per se. The avoided interpretation of value in many ESS assessments has made them scarcely credible from an economic point of view. The only way to reconcile economic value and ESS assessments is to consider marginal changes in ecosystems. This can be done with simulated experiments where increasing portions of ecosystems are modified and the relative effect on ESS is measured. This is also a way to identify possible tipping points in ecosystem functioning for ESS and include resilience. This usually requires time series data sets not often available and model integration capabilities.

- 8 **Means of validation:** Model validation against known data is a key best practice in modelling. In a statistical model, a measure of goodness of fit such as an R^2 value in a regression or a kappa value for land use/land cover classification can be used. However, to validate a model it is necessary to know what the true values should have been. This is difficult for some ESS, especially ones based on expert opinion and cultural services against which there are no objective values to test.

Additionally, simulation models of complex systems are inherently difficult to validate as a result of the unpredictability of complex systems, and also the lack of suitable independent datasets for comparison. With an increasingly instrumented world pushing the availability and use of “Big Data”, the challenge of appropriate data for both parameterisation and validation may be partially solved. Despite this increased data availability, there are persistent issues with determining if the difference between observed data and modelled data represents a real result, is due to system complexity, or is an artefact of modelling error. Robust testing of all model parameters for sensitivity might be a partial solution to validation concerns. However, this leaves ESS simulation models more open to critique of their scientific robustness especially if used with predictive purposes. The main problem is that the use of predictive models under conditions of deep uncertainty is highly problematic.

Exploratory modelling and analysis offers a systematic approach to explore synergies and trade-offs between different scenarios. Using computational models as generators of controlled experiments makes it possible to analyse complex social-ecological systems taking into account uncertainties (Kwakkel and Pruyt 2013). Unlike predictive modelling, the output of exploratory modelling and analysis does not provide a surrogate of the target system. Instead, it delivers a computational experiment inferring how the world would behave if the various estimates and assumptions were correct.

- 9 **Treatment of uncertainty:** Uncertainty is a key aspect of model interpretation: how sure are we that the model output represents the real world phenomenon it seeks to quantify? There are multiple elements of uncertainty, for example: (i) To what extent do the input datasets used to train the model reflect the conditions for which they are intended (data uncertainty)? (ii) To what extent does the model represent the processes that happen in reality (model uncertainty)? And (iii) for models forecasting the future, to what extent is that future likely to occur (scenario uncertainty)?

Model validation is often used to address model uncertainty. Inter-model comparison studies also reveal differences in outputs due to different model types. Probabilistic approaches and sensitivity analyses can also be used to address scenario and input data uncertainty by exploring the influence of input parameter changes on model outputs by performing multiple runs and identifying overall patterns. It is, however, rare that the full holistic uncertainty (that addresses all these factors) is addressed. A validation statistic may be produced that indicates, for instance, “this model explains 80% of the variation in the dataset we tested it against,” but this provides no information about the confidence in this dataset (was it randomly sampled, or taken from locations easily accessible by monitoring teams?); the factors within the model that provide the modeller with confidence in the approach taken (e.g., are there any subjectively selected adjustment factors?); or, the pragmatic factors such as time, expertise, and funding that shaped the model development.

We stress this because it is critically important that the context of the modelling is considered when interpreting its outputs for decision making. This is not to say that models are any more inherently flawed than any other way of understanding the environment. There will be some models, particularly those driven strongly by physical laws that can reliably and repeatedly reproduce real-world outcomes. We simply stress that models are simplifications of reality and should be interpreted with care. Whenever possible, model interpretation should take place with the assistance of the modeller (or someone who understands the model) and local stakeholders, who understand the context of its application.

- 10 **Learning curve:** As the time required applying a tool decreases, it becomes increasingly practical for widespread use in time sensitive decision-making processes. Since ESS models can belong to different domains of expertise, it is important to enable approaches that capture the complexity of description necessary to the simulation of coupled human-natural systems, without putting the burden of this complexity on users. But how to put sophisticated modelling capabilities at the fingertips of non-technical users, practitioners and decision makers, without imposing a steep learning curve? Information and communication technology is mature enough now to support tools that follow intuitive workflows consistent with what users normally experience while browsing the web. At the backend, they could access sophisticated and reusable model and data components through open-source modelling tools and paradigms. Machine-driven intelligence would therefore make very complex models usable for anyone with enough experience to read and interpret their results.
- 11 **Robustness:** Tools should be sufficiently developed to run reliably, use established models, produce replicable results, and have their methods, assumptions, strengths, and limitations well documented as part of a user manual and peer-reviewed journal articles, which may include validation exercises. Tools that are well-developed and documented have greater transparency and credibility, which can improve trust with decision makers and the public.

12 Targeted audience/community of users: The nature of the targeted end-users or developers communities is a key issue that must be taken into account when considering starting using a new modelling tool. Ideal modelling tools are as general and flexible as possible to suit the needs of both advanced and lesser skilled modellers (Martínez-López et al. 2015). In this regard, they should represent adequately documented software tools that can be useful for non-programmers, and they should be flexible enough so that advanced users can fully understand the role of each component and adapt them to case-specific requirements.

Conclusion: Based on our evaluation criteria from the modelling perspective, ESS and EBM tools should focus more on the capacity of studying multiple interactions and scenarios, rather than on developing individual finer scale models with more precise outputs.

Future development: About 20 years after its official debut (Costanza et al. 1997, Daily 1997), research on ESS has pervaded a number of disciplines from basic ecology to environmental economics. Perhaps for this reason ESS language has become a much utilised, and sometimes discordant, shared parlance within multidisciplinary research projects, where elements from the natural and the social sciences are combined to study the complexity of human-environmental systems. Indeed these kinds of studies often inquire about the sustainability of a certain region, and since sustainability encompasses both a goal state and the durability of this state over time (Waring et al. 2015), model-based computational experiments are employed to explore possible futures (Kwakkel and Pruyt 2013).

4.3.3 Systematic spatial prioritisation tools

The software Marxan

Marxan (Ball et al. 2009) is the most utilised conservation planning software worldwide (over 60 countries, 1100 users, and 600 organisations). Marxan solves the so-called minimum-set problem by selecting a set of parcels (i.e., pre-defined spatial planning units hereafter called planning units, PU) of land, river or sea from a pool of PUs that together build a network within which user-defined “targets” for each feature (biodiversity or ESS) are protected for the minimum cost (adapted from Gómez et al., 2017). Targets are the amount of each feature to select (e.g., 80% of each species’ occurrence that needs to be included in the network solution). Costs need to be defined for each spatial unit separately; they can be derived from, e.g. the extent of land area, land value, resource harvest value, cultural value, spiritual value, human impact, etc. The higher the cost for a PU, the less likely Marxan chooses this costly PU for the network. Marxan also allows the consideration and variation of the degree of compactness of the PU-network and the importance of meeting each feature target.

Why is protecting a network of sites important?

Establishing a spatially-explicit action plan based on EBM requires the consideration of various socio-economic objectives derived from stakeholder preferences as well as biodiversity conservation needs. Meeting all of these objectives, which are often conflicting each other and,

therefore, mutually exclusive, in an efficient and fair way is not possible with managing a single site or even a small group of sites. Hence, in order to address a complex multi-criteria problem, applying multiple actions on multiple sites is necessary.

What's behind the software?

Marxan is based on an objective function that is solved using an optimisation algorithm called simulated annealing. The algorithm minimises the objective function, i.e. tries to capture a maximum amount of features (as defined by the users) for the least cost (as opposed to, for example, the maximum coverage problem of capturing as much representation of features as possible with a fixed budget; see Zonation below). The objective function combines three cost elements: the combined PU costs, the combined target shortfall, i.e. the penalty for not achieving the pre-defined feature targets in the selected PU-network, and the combined connectivity shortfall, i.e. the penalty for not including neighbouring PUs. The set of PUs with the lowest score is the one that Marxan selects as the near-optimal solution.

Objective function

$$= \sum_{\text{planning units}} \text{Cost} + \text{SPF} \sum_{\text{features}} \text{Feature Penalty} + \text{CSM} \sum \text{Connectivity Penalty}$$

The Species Penalty Factor (SPF) and the Connectivity Strength Modifier (CSM) can be adapted to weight the different elements in the function.

How and when to involve interested parties such as planners, stakeholders and decision makers?

Planners must determine which features and how much of each feature (the targets) will be considered, and how data gaps and current limitations will be addressed. All decisions can be altered iteratively after the analysis. One of the most substantial advantages of Marxan from a user perspective is its ability to return multiple good (near-optimal) solutions that can be used for discussing solutions with interested parties. Marxan is a spatial planning tool to support decision-making (not to be confused with a decision support system), and it strongly depends on the conservation features and the targets. It will not produce a final network of reserves, and results must be fine-tuned to consider the full range of political, socio-economic and practical factors. Marxan can enhance the rigor, transparency and repeatability of decisions that are inherently complex and potentially subjective. Examples of studies that used Marxan are listed in Table 6.

Table 6: Examples of Marxan applications in aquatic realms in the literature

Aquatic realm	Reference	Title
Riverine	(Langhans et al. 2014)	Cost-effective river rehabilitation planning: optimising for morphological benefits at large spatial scales
	Langhans et al. (2016)	Coupling systematic planning and expert judgement enhances the efficiency of river restoration
	Hermoso et al. (2011)	Addressing longitudinal connectivity in the systematic conservation planning of fresh waters
Coastal	Costa et al. (2016)	Incorporating early life stages of fishes into estuarine spatial conservation planning
	Schmiing et al. (2015)	Marine conservation of multispecies and multi-use areas with various conservation objectives and targets
Marine	Ruiz-Frau et al. (2015)	A multidisciplinary approach in the design of marine protected areas: Integration of science and stakeholder based methods

What are the different steps to follow when applying Marxan?

- 1 Identify objectives of the case study together with decision makers and stakeholders
- 2 Identify which data is necessary to perform the planning exercise
- 3 Compile the available data in the case study area
- 4 Divide the case study area into PUs
- 5 Analyse species/habitat/conservation feature occurrence in each PU (use outputs from SDMs)
- 6 Analyse costs for each planning unit (e.g., derived from area, human footprint, opportunity costs etc.)
- 7 Set targets for each feature (consult decision makers and stakeholders)
- 8 Run Marxan, calibrate parameters
- 9 Link Marxan outputs with a visualisation software, e.g. ArcGIS or QGIS to map them
- 10 Reiterate analysis with new/updated data and/or constraints at any step

Marxan with Zones

Marxan with Zones is an extension of Marxan. The new element in the decision problem added in Marxan with Zones is that any PU cannot only be allocated to reserved or unreserved, but to a specific *management* zone. Each zone can be characterised by different actions, objectives, and restraints, one zone usually being the no-take or conservation only zone, while others would allow for ESS use. In addition, one can define the contribution of each zone to achieve the targeted features. Based on the same idea as in Marxan, i.e. optimising the minimum-set problem, the objective of Marxan with Zones is to minimise the overall costs of the zoning plan, while ensuring that the pre-defined feature targets are met (Watts et al. 2009). Hermoso et al. (2016) showed that when considering different management zones, as done when using Marxan with Zones instead of Marxan, 60% less area for strict conservation was needed to reach species targets (fish, amphibians and semi-aquatic reptiles) in the Iberian Peninsula. Hence, when considering biodiversity and ESS concurrently, Marxan with Zones is clearly preferred to Marxan as an optimisation method. Examples of studies that used Marxan with Zones are listed in Table 7.

Table 7: Examples of Marxan with Zones applications in aquatic realms in the literature

Aquatic realm	Reference	Title
Riverine	Hermoso et al. (2015)	Catchment zoning for freshwater conservation: refining plans to enhance action on the ground
	Hermoso et al. (2016)	Catchment zoning to unlock freshwater conservation opportunities in the Iberian Peninsula
Coastal	Mills et al. (2012)	Where do national and local conservation actions meet? Simulating the expansion of ad hoc and systematic approaches to conservation into the future in Fiji
Marine	Klein et al. (2010)	Spatial marine zoning for fisheries and conservation

What are the different steps to follow when applying Marxan with Zones?

- 1 Identify objectives of the case study together with decision makers and stakeholders
- 2 Identify which data is necessary to perform the planning exercise
- 3 Compile the available data in the case study area
- 4 Divide the case study area into PUs
- 5 Identify different management zones in the case study area (consult decision makers and stakeholders)
- 6 Analyse species/habitat/conservation feature occurrence in each PU (use outputs from SDMs)

- 7 Analyse ESS delivery in each PU (use outputs from Aries related to relative service (supply – demand))
- 8 Define targets for conservation features and ESS in each zone
- 9 Analyse costs for each planning unit (e.g., depending on the management action identified for the respective zone)
- 10 Run Marxan with Zones, calibrate parameters
- 11 Link Marxan outputs with a visualisation software, e.g. ArcGIS or QGIS to map them
- 12 Reiterate analysis with new/updated data and/or constraints at any step

The software Zonation

Zonation (Moilanen et al. 2009) is an alternative approach to Marxan that allows input features to be positively or negatively weighted. This enables the inclusion of both positively weighted features representing biodiversity, as well as negatively weighted features to be avoided, such as exposure or other threatening conditions. Hence, positively weighted features could be species, habitat, or bioregions, whereas for example fishing pressure, water abstraction or exposure to pollution are negatively weighted features (Allnutt et al. 2012). The major difference between Zonation and Marxan is that Marxan applies the minimum–set problem (see above), while Zonation bases the analyses on the maximal coverage problem, in which the objective is to maximise the amount of conservation benefit, given a fixed budget. Allnutt et al. (2012) compared outputs of Marxan and Zonation spatial plans to increase the protected area of Madagascar’s west coast, considering fishing pressure, exposure to climate change, and biodiversity (habitats, species, biological richness, and biodiversity value). They found that Zonation produced rapid conservation rankings across large, diverse datasets, while Marxan readily identified strict protected areas that meet representation targets and minimise exposure probabilities for conservation features at low economic cost. Since meeting targets is a feature that is needed in a prioritisation tool used in a project that aims at reaching policy goals (such as AQUACROSS), we recommend Marxan with Zones as the preferred method. However, target–based planning is now a feature in Zonation v4.0 too, although it is not the most common analysis model.

Criteria to consider when applying Marxan

Similar to the chapter on “Criteria to select ESS tools: a modeller perspective”, we present a non–exhaustive list of key criteria that most likely need to be considered as they play a role when applying a spatial prioritisation tool and assessing its outcomes.

- 1 **Defining conservation targets:** Targets can, but do not have to be, the same for each of the conservation features included in the planning analyses. However, the targets have to be defined in the same unit as the feature is measured in. For example, if the conservation features are species, measured as abundances, the targets have to be given in abundances (e.g., 60% of the total abundance). In the same analyses, conservation features can

comprise different elements, for example species and habitats. Targets have then to be applied appropriately, e.g. abundances for species and extent for habitats. Identifying and quantifying sensible targets is often difficult, since the relevant information such as for example required for the persistence of, e.g. species, is often unavailable. As a guideline, Levin et al. (2015) propose that flexibility in a planning solution is adequate when approximately 10–20% of the study area is considered irreplaceable, i.e. with selection frequencies over 90%. If the feature targets were set too low, very few areas were identified as irreplaceable, whereas when targets were set too high, too many planning units were selected as irreplaceable.

- 2 **Weighting of conservation features:** Depending on their importance, conservation features can be given different weights. Consequences of higher weights are higher costs of the overall planning solution, if the targets for the “important” species (i.e., the ones with the higher weights) are not reached. For instance, higher weights are sometimes assigned to endemic or rare species.
- 3 **Defining costs of planning units:** The most common and easiest way of assigning a cost to a planning unit is using its area as a surrogate, i.e. the larger the area of the planning unit, the higher the cost of including it in the planning solution. However, depending on data availability there are multiple other options, such as using the Human Footprint (Friedrichs et al., in review²⁸) or a landscape measure of catchment disturbance (i.e., the river disturbance index, Linke et al. (2012)) as a surrogate for costs. When choosing the type of cost, it should always be kept in mind that Marxan tries to minimise the objective function; hence, planning units with higher cost are less likely to be included in the planning solution.
- 4 **Type of output and interpretation:** The two most important output files Marxan produces are: 1) The best solution and 2) the irreplaceability file. 1) This file depicts all planning units and whether or not they are included in the best solution with binary values (selected = 1 or not selected = 0). The values are usually visualised as a spatial map. When Marxan is run in R, the map of the best solution is produced automatically, while outputs from running the standard Marxan.exe file need to be linked to a geographic information system like ArcGIS or QGIS in order to be visualised. 2) The irreplaceability file shows how often a spatial planning unit is selected out of the maximum number of runs (e.g., 100). These numbers are often used as an indicator of how important a planning unit is to reach the given feature targets (e.g., a planning unit chosen a 100 times out of the 100 runs is more important to reach the feature targets than a planning unit which is only chosen 50 times). However, it always has to be clear that, to fully reach the defined targets, all selected planning units identified in a best solution have to be considered for conservation/restoration.

²⁸ Friedrichs, M., Hermoso, V., Langhans, S.D. (in review). Evaluation of habitat protection under the European Natura 2000 conservation scheme.

- 5 **Spatio-temporal scale:** Marxan and Marxan with Zones are very flexible in terms of how many planning units can be included, although a maximum number of 50,000 should not be exceeded (Ardron et al. 2008). The extent of each planning unit should be defined according to the purpose of the spatial planning, i.e. planning units that are too large may not be appropriate to be implemented on ground (Langhans et al. 2016). However, since the software use static images of the current or predicted status of target features as input data, they are somewhat limited in the consideration of temporal dynamics.
- 6 **Cross-realm planning:** Despite progress in the theory of cross-realm planning, only a few fully integrated and applied plans exist so far (Álvarez-Romero et al. 2015). Begeer et al. (2010) for example, account for the connectivity between terrestrial, marine, and freshwater systems considering four types of connectivity: 1) narrow (e.g., riparian buffer strips) and 2) broad interfaces (e.g., estuaries), 3) constrained connections (e.g., corridors of native vegetation used by amphibians to move between natal ponds and adult habitat), and 4) diffuse connections (e.g., movements of animals between breeding and feeding habitats). In spatial planning analyses, narrow interface can be accounted for by “(a) including them incidentally by targeting environments around them, (b) representing the interface as a linear feature, (c) configuring planning units specifically to define the interface, (d) applying stratification to conservation features in interface habitats, and (e) using smaller planning units in interface habitats to recognise the higher spatial heterogeneity in features of interest at those interfaces” (Begeer et al. 2010). Álvarez-Romero et al. (2015) go a step further offering a framework to operationalise real-world planning based on information given by scientists, resource managers and policy-makers. In a collaborative process they identify the most relevant uses of and threat propagation pathways among different realms to be included in the planning process.
- 7 **Treatment of uncertainty:** Mapping errors of conservation features are rarely accommodated in planning processes despite being the most pervasive forms of data uncertainty used to make conservation and management decisions (Tulloch et al. 2013). Habitat-mappings are often used as a surrogate for biodiversity in conservation and management schemes (Brink et al. 2016, Martínez-López et al. 2016). Tulloch et al. (2013) used information of the probability of occurrence of different coral reef habitats, derived from remote sensing data, to design a marine reserve network and showed that priority areas change in the probabilistic approach. Similarly, uncertainty in species occurrences should be captured with and included in the spatial optimisation analyses as probability of occurrences, instead of using binary presence/absence information.
- 8 **Targeted audience/community of users:** The audience of Marxan and Marxan with Zones comprises researchers interested in nature conservation issues, practitioners and decision makers. See also point 9.
- 9 **Network of users:** Due to the fact that the developers of Marxan have left the University of Queensland and taken on other jobs, the software is currently abandoned. The future of the software is, however, under discussion and is likely to be financed through a

consortium of users. Questions related to the application of the software are still answered by the community through the mailing-list.²⁹

- 10 Software downloads and teaching material:** Marxan and Marxan with Zones can be downloaded³⁰ free of charge. Marxan good practices handbook³¹ in English and Spanish and should be consulted before using the software for appropriate handling. Training courses are announced through PacMARA.³² Zonation including software, manuals, presentations, and example setups can also be downloaded.³³

²⁹ <http://marxan.net/index.php/emaillist>

³⁰ <http://marxan.net/software>

³¹ <http://pacmara.org/mgph-v2>

³² <http://pacmara.org/events-workshops>

³³ <https://www.helsinki.fi/en/researchgroups/metapopulation-research-centre/software>

5 Scenarios

A **scenario** is "a coherent, internally consistent, and plausible description of a potential future trajectory of a system" (Gómez et al., 2017). Many scenario–planning processes aim to identify policy recommendations for sustainable development (Cork et al. 2005, Palomo et al. 2011). Management or policy scenarios are often developed jointly with stakeholders in participatory processes in order to enable social learning and develop a shared understanding of the social–ecological system and possible future development pathways. Scenario planning can foster collective action to achieve desired goals and explore how stakeholders might respond to future challenges and change (Bohnet and Smith 2007, Kok et al. 2007, Wollenberg et al. 2000). Finally, scenario planning can support a societal process of defining the bundles of ESS and biodiversity targets that are desired in the future.

Important aspects to consider when developing and using scenarios and scenario planning processes are (Gómez et al. 2016, Gómez et al. 2017; Deliverable 3.2):

- ▶ Scenarios are means rather than ends. Besides representing the best available knowledge to understand and assess the system (a positive approach to scenarios), scenarios are powerful decision–support instruments aimed at providing better political responses to prevailing policy challenges associated to ecosystems and biodiversity management (a normative approach to scenarios). They can also facilitate processes of social learning, which may lead to enhanced understanding of the social–ecological system and improved, possibly more integrated, management.
- ▶ Scenarios are representations of possible trajectories of the social–ecological system. According to the AQUACROSS concept and framework, they are means to make the AQUACROSS architecture operational and they are built following the AQUACROSS heuristics (Gómez et al. 2016; Deliverable 3.1, Gómez et al. 2017; Deliverable 3.2). They play an important role in the case studies to help identify policy objectives, means to reach them and possible consequences and uncertainties taking both the best available scientific knowledge and stakeholder preferences and societal goals into account.

5.1 Types of scenarios within AQUACROSS

AQUACROSS distinguishes between **baseline** and **policy** scenarios (see Gómez et al. (2017; Deliverable 3.2)). A baseline scenario is a shared view of current trends and vulnerabilities in ESS and biodiversity and associated challenges in a case study. The policy or management scenario focuses on alternative potential solutions and can represent alternative pathways for reaching a target (normative) or represent and assess the outcomes of several alternative policy instruments or measures (descriptive). In AQUACROSS, policy scenarios focus around pathways to achieve.

It is important to point out that baseline and policy scenarios are interlinked. Baseline scenarios must be policy-relevant as they are functional to assess the social-ecological system, and thereafter, to identify policy challenges and to agree on policy objectives. They thus form the basis for the development of policy scenarios that are alternative futures of the system. The development of a baseline scenario is critical to identify shared visions and goals but also those social and ecological elements and processes (the AQUACROSS butterfly, Gómez et al., 2016) that are important for achieving them, as well as the scientific knowledge that has the highest potential to inform and improve policy responses.

The term “scenarios” is used very broadly in different communities to refer to either quantitative, data- or model driven assessments of possible future developments, or qualitative narratives of alternative futures. Whether the final scenario is quantitative or qualitative, it should always be based on the best available knowledge of the current state of the social-ecological system and major social and ecological processes driving its development as well as the knowledge, beliefs and perceptions of stakeholders (Caudron et al. 2012). This will necessarily always include quantitative (e.g., population trends) and qualitative (e.g., planned measures, preferences of stakeholders) information that then needs to be translated into the scenario. Scenarios are thus the result of a scenario development process that brings together knowledge and assumptions about trends in drivers and pressures, planned (baseline scenario) or alternative (policy scenario) policies into an “image of how the future may unfold” (IPCC 2000). Stakeholder involvement is particularly relevant when it comes to identifying the desired set of ESS and biodiversity targets as well as associated governance challenges (Robards et al. 2011). It is however, also essential to include stakeholders’ knowledge of the social-ecological system to identify critical processes and leverage points. More information on methods to develop scenarios and the current and future development and use of scenarios in the AQUACROSS case studies can be found in Deliverable 7.2 (due in 2017).

5.2 Scenarios in the case studies

The purpose of building and using scenarios in the AQUACROSS case studies needs to be aligned with the objectives of the case study and the research and stakeholder processes. It is important to properly define the temporal, institutional and spatial scale of each case study to be able to distinguish between external (that are beyond influence by actors in the case) and endogenous processes. Scenarios can be used to assess the consequences for ESS and biodiversity of changes in external conditions such as climate or for assessing potential future endogenous pathways resulting from alternative policies.

All scenarios include and explicitly consider the future development of high-level processes (such as demography, climate change, adaptation, technological progress, etc.). These processes (that are not “external drivers”, see Pletterbauer et al. (2016; Deliverable 4.1)), are critical to understand interactions at the case study level and will be essential to assess the effectiveness, efficiency, etc. of any EBM or policy response. That is to say, these external factors are not alternative scenarios but critical elements of any baseline or policy scenario. Otherwise, case study scenarios would deal with the study of processes artificially detached

from the rest of the planet and its civilisation. Notwithstanding that, a clear identification of which high-level processes are relevant and which are not is an important task in any case study (a task that can be accomplished in building the baseline).

The identification of biodiversity and ESS targets needs to be the result of a societal process. The assessment of desired flows of ESS and measures to sustain them is, however, difficult as some ecosystem states and services may be more desired by some people than others. The planning and allocation of flows of ESS and benefits from biodiversity conservation are thus subject to asymmetries, power dynamics and political struggles between groups of people (Robards et al. 2011). Careful attention needs to be directed to understanding trade-offs and developing a process that is sensitive to these issues. Participatory scenario development or scenario planning can, when implemented well, help elicit and navigate different interests towards the development of shared ESS and biodiversity goals.

In the Rönneå catchment, for instance, a stakeholder process in the form of three workshops at municipality and regional levels was carried out to develop scenarios about future ESS provision. The aim was to understand the social-ecological system in the catchment and how water governance can be improved to foster ESS supply. In the workshops, exercises alternated between involving homogenous and diverse groups with people from different sectors in municipalities (e.g., drinking water, storm water) and on a regional water governance level (e.g., county administrative board, water councils, landowners and water authorities). Thereafter, group interviews were conducted in focus groups with exercises that activated participants and created conditions for in-depth discussions (Colucci 2007). Each focus group had one facilitator and a table template. Participants discussed the links between 1) policy goals (one water related, and one non-water related), 2) measures needed to achieve those goals and, 3) interactions (synergies, trade-offs and one-directional relationships) with ESS. Starting with an end-goal and discussing potential pathways and outcomes is called 'back-casting' and is commonly used to explore how desirable futures may be reached (Carlsson-Kanyama et al. 2008).

The linkage framework allows any scenarios to be put in the context of the wider system. For example, by focusing on a change in state of a particular ecosystem component, the linkage framework can be used to check all of the ESS, which may be affected by a change in the state of that component. All of the pressures and primary activities, which may lead to a change in state, can also be checked. Thus, for any given scenario where there is a change in the state of an ecosystem component, management options can consider which activities and pressures to target, and can make trade-offs against any potential changes in ESS.

The linkage framework can also be used with stakeholders to co-build scenarios. For example, in one of the AQUACROSS case studies, the Lough Erne system, the linkage framework will be used to help frame the system with stakeholders, highlighting different activities and ecosystem components present, and discussing with stakeholders potential interactions between those, from their perspective. This will then be used to develop scenarios and management options that are relevant to the goals of the stakeholders.

6 Model Coupling: Combining Biodiversity, Ecosystem Functions and Ecosystem Services within the Spatial Prioritisation

Marxan with Zones uses a simulated annealing optimisation algorithm to try to minimise an objective function similar to Marxan (Ball et al. 2009). The objective function in Marxan is composed of three different parameters: i) the cost associated to the management of all planning units in the solution, ii) penalties for not achieving targets for all conservation features (e.g., species and/or habitats), and iii) connectivity penalties for missing connections, along the river network in freshwater studies (Hermoso et al. 2011). In this way, the overall cost of representing all conservation features in a connected network of priority areas is minimised. The objective function used in Marxan with Zones is slightly more complex as there is more than one management zone (see Watts et al. (2009) for further detail on the mathematical formulation of Marxan with Zones) and so there are penalties for missed targets for each zone or connectivity both within and across zones.

The prioritisation will be carried out on the datasets delivered by previous steps: maps of spatial distribution of biodiversity, and EF and ESS. As mentioned above, two different management zones will be considered: a management zone for representing biodiversity conservation as well as a compatible ESS zone, to address co-benefits, and a management zone to address potential trade-offs between granting access to provisioning services and the maintenance of biodiversity/compatible ESS. Representation targets will be set for both, biodiversity (e.g., proportion of their current/future distribution) and ESS (e.g., proportion of total potential for a service or amount needed to cover the demand in the case of provisioning services). Given the different role that each management zone will have been assigned, representation targets for biodiversity and compatible ESS will be achieved in the management zone devoted to maximising co-benefits between these features, while the targets for the provisioning services will be linked to the management zone to deal with trade-offs. In this way targets for provisioning services, for example, will not be represented within the management zone devoted to conservation purposes. This does not mean that there will not be potential for provisioning services within this management zone, but that the target or demand for these services will be granted somewhere else, within its specific management zone whenever possible.

The prioritisation process will try to find the best allocation for the different management zones so the targets can be achieved whenever possible while accounting for costs of implementing those management options and other spatial constraints like connectivity (see below). Co-benefits will be addressed by seeking spatial overlap of priority areas for conservation and the maintenance of compatible ESS. On the other hand, trade-offs will be addressed by looking for areas where the access to provisioning ESS could be granted. This management zone would have the only purpose of covering the demand for these provisioning services. The spatial arrangement of these management zones will be designed to address special conservation needs in freshwater ecosystems, such as longitudinal connectivity. Connectivity will play a special role to ensure not only internal contiguity within each management zone, so key ecological processes are maintained in conservation zones for example, but also between zones. In this later case, the aim will be to try to minimise the potential impact of management zone for provisioning services on the other management zone, by allocating it as disconnected as possible.

6.1 Iterate, adjust and predict models under different scenarios

After combining SDMs and ESS models within Marxan with Zones, the sensitivity of the spatial prioritisation outputs should be tested against different settings regarding targets and costs. This iteration of re-running the models helps to identify possible weaknesses in the optimisation procedure. At this point, involving stakeholders should be considered to seek advice on case study-specific modifications within the spatial prioritisation (e.g., certain species of importance, setting costs and targets for specific species, EF and ESS).

The combination and joint prioritisation of biodiversity, EF and ESS is useful for revealing interactions and trade-offs among the single components. In addition, the comparison of outcomes of management scenarios assuming traditional or innovative management approaches aims to identify also the potential costs that are associated between these two options. When iterating and testing such options, determinism should be avoided while balancing between long-term forecasts and uncertainties in the assumptions might help to create new management solutions (Gómez et al. 2017; Deliverable 3.2 chapter 2.1.1). Comparing the outcomes of different management scenarios (e.g., baseline/inaction vs. alternative policy decisions) can then reveal which management options could provide the optimal solutions regarding the management targets within the specific case study area (Gómez et al. 2017; Deliverable 3.2 chapter 1.3.6).

This comprehensive analysis contributes to an increased visibility of the possible costs of ecosystem degradation and biodiversity decline, opposed to the benefits of their preservation. Representing the outcomes of such analyses to inform stakeholders can then be used to increase awareness of the consequences of their own management decisions (Gómez et al. 2017; Deliverable 3.2, chapter 2.1.2).

Within the spatial modelling workflow, there is obviously the need to incorporate policy options that may be in a non-spatial format (e.g., an envisaged percent increase in a certain agriculture within a given catchment or drainage basin). Such non-spatial information can be translated into spatial layers of, e.g. land cover change, either by expert-opinion by highlighting areas that will be impacted by agriculture (analogous to expert range information of species occurrences), or by using land use change models (e.g., the CLUMondo model, Eitelberg et al., 2016) that allow to model the spatially-explicit changes in land cover given the policy options. CLUMondo comes with a Graphical User Interface that enables a quick implementation and virtualisation of various model runs, hence also yielding the prerequisite for assessing uncertainties deriving from different parametrisation. This means that for a given policy option, various versions of spatial layers can be created, and tested how these might impact the prioritisation of BD, EF and ESS.

Other policy options, leading to potential changes in, e.g. hydrology, hydromorphology, tourism, etc. can be translated in a similar way, yielding spatial layers of such changes. Regarding e.g. policy options such as catch / effort control in fisheries, we propose this could be implemented in the models through a spatial layer, indicating areas where the policy option is implemented: the lack of catch / effort control might have a detrimental impact in the species, and thus the spatial layer penalises the occurrence probability of the species at those locations.

6.2 Advantages of the spatial modelling framework

Jointly accounting for biodiversity, EF and ESS within one framework enables to assess patterns that can be further analysed to disentangle potential causalities among these components. The spatial prioritisation under a baseline can be compared to alternative courses of action (e.g., under management scenarios) to assess possible differences where EBM would or would not have been applied. According to Gómez et al. (2017; Deliverable 3.2, e.g. chapter 2.1.1, page 35), a baseline scenario is not necessarily equivalent to a scenario (only) describing the current situation, but rather the trend if there is no action (towards 2020 and 2030). In other words, it is not what is happening today, but rather what would happen if the different drivers exert pressures over European aquatic ecosystems following a specific trend, a pathway from today to 2020 and 2030, which is to be assessed.

Assessing the impact of possible scenarios on biodiversity, ESS and in the joint prioritisation is a powerful tool to explore the optimal EBM within the case study area (which is also effective in terms of dissemination). To start, the upper and lower range of potential future pathways set the frame/window of possible outcomes (Gómez et al. 2017; Deliverable 3.2, chapter 2.1.1). Moreover, the assessment of scenarios allows to (i) confront stakeholders and institutions with the outcomes of their current decisions and, (ii) support collective decision-making to integrally manage ecosystems by comparing and assessing alternative courses of action

(Gómez et al. 2017; Deliverable 3.2, chapter 2.1.4). In summary, this approach supports a knowledge-based decision-making process, with increased relevance, credibility of social knowledge and legitimacy of policy decisions it intends to inform and improve (Gómez et al. 2017; Deliverable 3.2, chapter 2.1.3, pages 39–42).

7 Assessing Uncertainties

As described in Gómez et al. (2017; Deliverable 3.2), different sources of uncertainty have to be considered when modelling the impacts of drivers of change on biodiversity, EF and aquatic ESS.

Uncertainty about future socio-economic development can be addressed by the development of scenarios that describe possible future states and deriving probabilistic model predictions conditional under these scenarios. Uncertainty about future change of drivers that represent environmental influence factors in the models (i.e., model input uncertainty) can be propagated through the model (e.g., with Monte Carlo simulations). In addition to input uncertainty, uncertainty regarding the response of the modelled variables (e.g., descriptors for biodiversity, ESS delivery) to changes in drivers includes parameter uncertainty and intrinsic stochasticity.

Ideally, the model is formulated based on prior knowledge about processes and parameters (from literature, expert knowledge) and updated based on observed data of the investigated system in a Bayesian framework (Balbi et al. 2016). This should be done taking into account observation error by specifying an appropriate likelihood function. Cross-validation methods allow the assessment of the predictive capacity of the models with independent data.

We refer to Gómez et al. (2017; Deliverable 3.2) for analytical approaches and guidance, different sources of uncertainty, and how to deal and assess them.

8 Alternatives

The crucial part of applying such a modelling workflow is the availability of appropriate biodiversity, EF and ESS data that is able to represent the targeted outcome. However, the data quality and quantity in different case study areas is heterogeneous, where perhaps the biodiversity component is well covered but not the ESS side, or vice versa. In this chapter, we aim to give guidance and recommendations if, and how, the biodiversity, EF and ESS models along with the spatial prioritisation could be used nevertheless. A minimum set of requirements varies strongly and depends on the given case study area, and hence needs to be assessed individually for each case study.

8.1 Alternatives within the modelling framework

Likewise to the models used in WP5 (causal flow indicators between biodiversity, EF and ESS (Nogueira et al. 2016; Deliverable 5.1), performing the biodiversity and ESS models in a Bayesian framework would represent the most promising way, as this would allow to fully account for the uncertainties from both components in the spatial prioritisation process due to the Markov Chain Monte Carlo sampling. This is, however, not feasible in many cases due to the data quality (needs to stem from survey data with repeated visits) and possible violations of the closure assumption.

Regarding the biodiversity component, the species data may not allow the creation of a statistical relationship between the response and explanatory variables (see chapter 4.1.1) due to, e.g. a very limited number of occurrences per species, so several alternatives may provide an approximation of the expected diversity patterns:

The so-called “bioclim” model (Booth et al. 2014, Busby 1991) creates an “environmental envelope” and broadly defines and maps the distribution of a species across the study area. The principle is based on the point records that fall within the range of values for each environmental predictor. The more predictors are used, the more constrained the mapped distributions are.

Though expert range information is prone to overestimate the fine-scale, e.g. species richness, these maps are however useful to delineate biodiversity gradients over large spatial extents.

If SDMs or none of the previous solutions are feasible, a possible alternative could be to use existing biodiversity data layers (e.g., species or functional richness/diversity). Although this would not be the optimal setting, the spatial prioritisation can be adjusted to run on such aggregated maps (instead of per species) to provide an approximation in the spatial patterns.

It is important to note that such approaches do not provide any probability of occurrence (but only a presence layer of the species) or any measures of uncertainty, neither model- nor data-driven uncertainties. Yet, such simple tools may be useful to approximate the biodiversity patterns within the study area. In addition, when downgrading the models and the modelling framework, the key assumptions and expectations of the outputs need to be adjusted as well to meet the input data.

Regarding the ESS component, the best option is to create case-study specific ESS layers in a Bayesian framework, yielding the uncertainties in the spatial ESS patterns (allowing to be combined with those deriving from SDMs to provide joint uncertainty maps). There may not be always the option to create the custom ESS layers for each case study area due to data availability or technical constraints. In such case, comparing the required input data for specific ESS models (see chapter 4.3.2 and Sharps et al. (2017)), or using readily available baseline

layers such as the MAES dataset³⁴ (Maes et al. (2012) could provide a solution. Such data, however, hampers the ability to apply and compare management scenarios, which themselves consist of alternative pathways represented by the ESS layers as in the baseline, but under different EBM assumptions. In other words, the ESS layers need to be computed for a given scenario as well.

8.2 Semi-quantitative risk-based approach

The linkage framework itself, as described in Pletterbauer et al. (2016; Deliverable 4.1) and Nogueira et al. (2016; Deliverable 5.1), can be used as the basis for exploratory analysis of the system, including simple network analyses. By simply taking the linkage matrices, it is possible to examine the complexity and connectivity in the aquatic ecosystem. Knights et al. (2013) have explored this, using analyses taken from food-web ecology and network analysis theory. This helps to highlight aspects such as which primary activities interact with most ecological components, which pressures are most pervasive in the system in terms of connectivity between activities and ecological components, and where are there similarities between sectors and/or pressures in terms of how they interact with the ecological components of the ecosystem.

A pressure assessment methodology (Knights et al. 2015, Robinson et al. 2014, Robinson et al. 2013) could also be used to weight the interactions between primary activities, pressures and ecological components based on the exposure, severity and recovery lag associated with each interaction in order to focus management on the greatest threats to policy objectives (Table 8). This recognises that not all activities undertaken are necessarily harmful to the same extent. By centering the approach on pressures, it is possible to focus on the most damaging aspects of primary activities and thus to target management strategies with a higher level of precision. Threats based on the pressure assessment can be summarised as risks (Knights et al. 2015) and then linked to management options to evaluate their effectiveness (Piet et al. 2015). This approach³⁵ is described in Robinson et al. (2014).

Other analyses can include the bow-tie approach (Smith et al. 2016), where tipping points are identified, along with threats that may cause a tipping point and consequences of an event. Different scenarios can be explored from different perspectives – as described in the scenarios section, and these can be used to weight the interactions from these different perspectives, while at the same time, placing them in the wider context of the full network to check for possible missing but important elements.

³⁴ <https://data.jrc.ec.europa.eu/collection/maes>

³⁵ www.odemm.com

	Description	Percent overlap (%)	Standardised value (proportion of max)
Spatial extent	The spatial extent of overlap between a pressure type and ecological characteristic		
Widespread	Where a sector overlaps with an ecological component by 50% or more (max is 100%).	75	1.00
Local	Where a sector overlaps with an ecological component by >5% but <50%. A raw value taken as the midpoint between the range boundaries	27.5	0.37
Site	Where a sector overlaps with an ecological component by >0% but <5%. A raw value taken as the midpoint between the range boundaries	2.5	0.03
Months per year			
Frequency	How often a pressure type and ecological characteristic interaction occurs measured in months per year		
Persistent	Where a pressure is introduced throughout the year	12	1.00
Common	Where a pressure is introduced up to 8 months of the year	8	0.67
Occasional	Where a pressure is introduced up to 4 months of the year	4	0.33
Rare	Where a pressure is introduced up to 1 month of the year	1	0.08
Severity per interaction			
Degree of Impact	An acute (A) interaction is an impact that kills a large proportion of individuals and causes an immediate change in the characteristic feature. A chronic (C) interaction is an impact that could have detrimental consequences if it occurs often enough and/or at high enough levels. A low severity (L) interaction never causes high levels of mortality, loss of habitat, or change in the typical species or functioning irrespective of the frequency and extent of the event(s)		
Acute	Severe effects after a single interaction	1	1.00
Chronic	Severe effects occur when the frequency of introductions exceed a specified number of interactions. Here, that critical value was specified as 8 occurrences (or $1/8 = 0.125$)	0.125	0.13
Low	Severe effect not expected. For precautionary reasons, we assume a potential effect after 100 introductions	0.01	0.01
Persistence (years)			

Persistence			
	The period over which the pressure continues to cause impact following cessation of the activity introducing that pressure		
Continuous	The pressure continues to impact the ecosystem for at least 100 years	100	1.00
High	The pressure continues to impact the ecosystem for between 10 and 100 years. A raw value taken as the midpoint between the range boundaries	55	0.55
Moderate	The pressure continues to impact the ecosystem for between 2 and 10 years. A raw value taken as the midpoint between the range boundaries	6	0.06
Low	The pressure continues to impact the ecosystem for between 0 and 2 years. A raw value taken as the midpoint between the range boundaries	1	0.01
		Recovery (years)	
Resilience			
	The resilience (recovery time) of the ecological characteristic to return to pre-impact conditions. Recovery times for species assessments were based on turnover times (e.g., generation times). For predominant habitat assessments, recovery time was the time taken for a habitat to recover its characteristic species or features given prevailing conditions		
None	The population/stock has no ability to recover and is expected to go “locally” extinct. The recovery in years is predicted to take 100+ years	100	1.00
Low	The population will take between 10 and 100 years to recover. A raw value taken as the midpoint between the range boundaries	55	0.55
Moderate	The population will take between 2 and 10 years to recover. A raw value taken as the midpoint between the range boundaries	6	0.06
High	The population will take between 0 and 2 years to recover. A raw value taken as the midpoint between the range boundaries	1	0.01

Table 8: The pressure assessment criteria and categories used to evaluate each impact chain and the numerical risk scores assigned to each category

9 Outlook

The tools and techniques presented in this report provide an approach that allows (i) integrating the causal relationships identified in WP4 and WP5 within one workflow, (ii) including scenario analyses, (iii) integrating stakeholder interactions by setting the targets as well as during the iteration of the modelling framework to (iv) ultimately achieve a greater transparency and credibility in the policy context and foreseeing biodiversity conservation and EBM in the case study areas.

Depending on the aim (qualitative vs. data-driven) and the data availability, the linkage framework and/or the spatial modelling framework can be applied in the case study areas. As currently taking place in WP5, the linkages and dependencies within and among the biodiversity, EF and ESS components need to be explored first. Building on that knowledge, and if data (quality and quantity) allows, models can be applied to gain more information regarding the spatial patterns, the uncertainties involved in the data and models, and to assess the impact of EBM scenarios on biodiversity, EF and ESS as well as in a joint analysis.

One central aim and advantage of the proposed modelling framework is the possibility to account for uncertainties stemming from the biodiversity side and the ESS side separately as well as combined within the spatial prioritisation process. This enables to communicate possible weaknesses and data-deficiencies to stakeholders.

All data and outcomes from the models in the case studies will be available on the Information Platform³⁶ and shared among project partners. Ad-hoc practical guidance on the proposed spatial modelling framework will be made available for selected case studies.

³⁶ dataportal.aquacross.eu/

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1 June 2015 to 30 November 2018

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